

Campus de Gualtar 4710-057 Braga



## **Computer Organization and Architecture**

5th Edition, 2000

by William Stallings



## I. OVERVIEW.

- 1. Introduction.
- 2. Computer Evolution and Performance.

**II. THE COMPUTER SYSTEM.** 

3. System Buses. 4. Internal Memory. 5. External Memory. 6. Input/Output. 7. Operating System Support.

**III. THE CENTRAL PROCESSING UNIT.** 

8. Computer Arithmetic. 9. Instruction Sets: Characteristics and Functions. 10. Instruction Sets: Addressing Modes and Formats. 11. CPU Structure and Function. 12. Reduced Instruction Set Computers (RISCs).

13. Instruction-Level Parallelism and Superscalar Processors.

**IV. THE CONTROL UNIT.** 

14. Control Unit Operation.

- 15. Microprogrammed Control.
- V. PARALLEL ORGANIZATION.

16. Parallel Processing. Appendix A: Digital Logic. Appendix B: Projects for Teaching Computer Organization and Architecture. References. Glossary. Index. Acronyms.



## **III. THE CENTRAL PROCESSING UNIT.**

8. ... 9. ... 10. ... 11. ... 12. ...

13. Instruction-Level Parallelism and Superscalar Processors. (5-May-01)

## Overview (13.1)

- Superscalar refers to a machine that is designed to improve the performance of the execution of scalar instructions
  - This is as opposed to vector processors, which achieve performance gains through parallel computation of elements of homogenous structures (such as vectors and arrays)
  - The essence of the superscalar approach is the ability to execute instructions independently in different pipelines, and in an order different from the program order.
  - In general terms, there are multiple functional units, each of which is implemented as a pipeline, which support parallel execution of several instructions.
- Superscalar vs. Superpipelined
  - Superpipeline falls behind the superscalar processor at the start of the program and at each branch target.



- Limitations
  - Superscalar approach depends on the ability to execute multiple instructions in parallel.
  - Instruction-level parallelism refers to the degree to which, on average, the instructions of a program can be executed in parallel.
- Fundamental limitations to parallelism (to which we apply compiler-based optimization and hardware techniques)
  - o True data dependency
    - Also called flow dependency or write-read dependency
    - Caused when one instruction needs data produced by a previous instruction
  - Procedural dependency
    - Usually caused by branches, i.e. the instructions following a branch (taken or not taken) cannot be executed until the branch is executed
    - Variable length instructions cause a procedural dependency because the instruction must be at least partially decoded (to determine its length) before the next instruction can be fetched.
  - Resource conflicts
    - A competition of two or more instructions for the same resource oat the same time.
    - Resources include memories, caches, buses, register-file ports, and functional units.
    - Similar to data dependency, but can be
      - overcome by duplication of resources
      - minimized by pipelining the appropriate functional unit (when an operation takes a long time)
  - o Output dependency
    - Only occurs when instructions may be completed out of order
    - Occurs when two instructions both change the same register or memory location, and a subsequent instruction references that data. The order of those two instructions must be preserved.
  - o Antidependency
    - Only occurs when instructions may be issued out of order
    - Similar to a true data dependency, but reversed
    - Instead of the first instruction producing a value that the second instruction uses, the second instruction destroys a value that the first instruction uses

