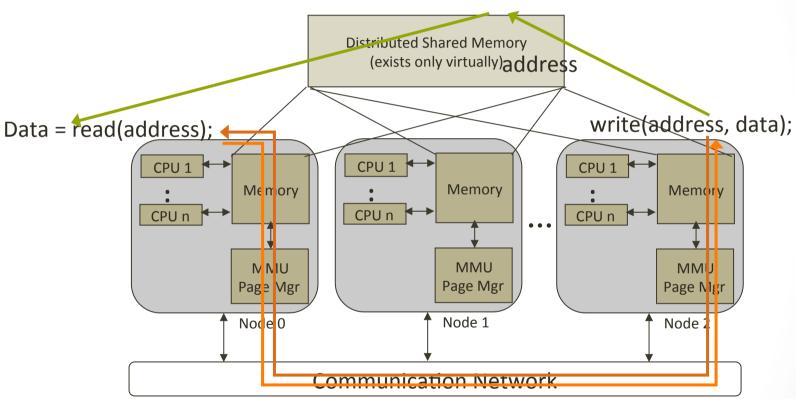
Distributed Shared Memory (DSM)

28-Nov-2017

DSM Basics



A cache line or a page is transferred to and cached in the requested computer.

Simple example

```
shared { int a, b; };
struct
Program Writer:
          main()
                       struct shared *p = (struct shared *) allocShared(...)
                       p->a=p->b=0; /* initialize fields to zero */
                                                { /* continuously update structure fields */
                       while(TRUE)
                                    p -> a = p -> a + 1;
                                   p -> b = p -> b - 1;
Program Reader:
           main()
                       struct\ shared\ *p = \dots
                       while(TRUE) {
                                              /* read the fields once every second */
                                    printf("a = \%d, b = \%d\n", p \rightarrow a, p \rightarrow b);
                                    sleep(1);
```

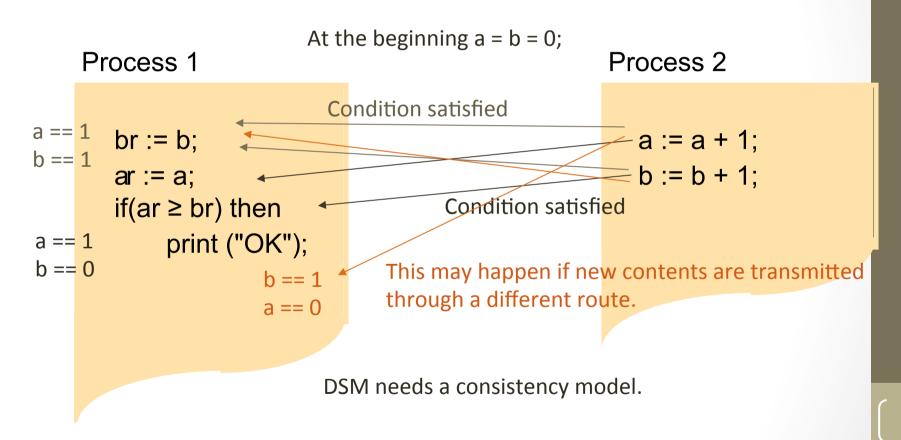
Why DSM

- Simpler abstraction
 - Underlying tedious communication primitives shielded by memory accesses
- Better portability of distributed programs
 - Natural transition from sequential to distributed application
- Better performance of some applications
 - Data locality, one-demand data movement, and large memory space reduce network traffic and paging/swapping activities.
- Flexible communication environment
 - Sender and receiver have no need to know each other. They even need not coexist.
- Ease of process migration
 - Migration is completed only by transferring the corresponding PCB to the destination.

Main Issues

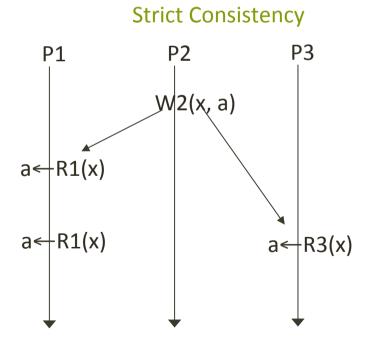
- Granularity
 - Fine (less false sharing but more network traffic)
 - Cache line (e.g. Dash and Alewife), Object (e.g. Orca and Linda), Page (e.g. Ivy)
 - Coarse(more false sharing but less network traffic)
- Memory consistency and access synchronization
 - Strict, Sequential, Causal, Weak, and Release Consistency models
- Data location and access
 - Broadcasting, centralized data locator, fixed distributed data locator, and dynamic distributed data locator
- Replacement strategy
 - LRU or FIFO (The same issue as OS virtual memory)
- Thrashing
 - How to prevent a block from being exchanged back and forth between two nodes.
- Heterogeneity
- Implementation
 - hardware implementation, OS implementation, and User-level implementation.

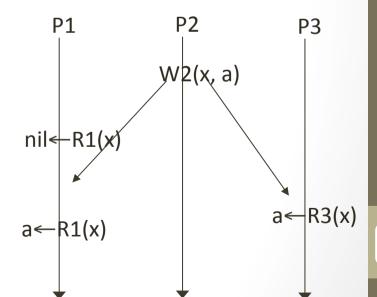
Two processes accessing shared variables



Strict Consistency

- Wi(x, a): Processor i writes on a variable x, (i.e., x = a;).
- b \leftarrow Ri(x): Processor i reads b from variable x. (i.e., y = x; && y == b;).
- Any read on x must return the value of the most recent write on x.

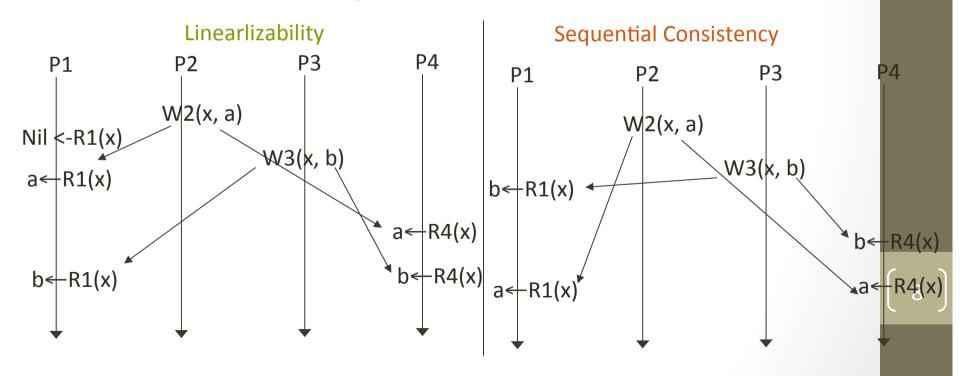




Not Strict Consistency

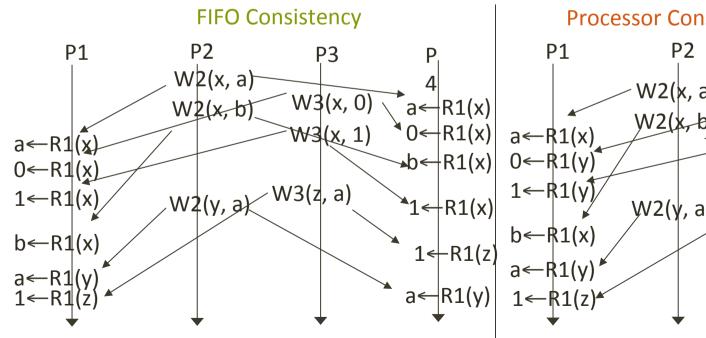
Linearizability and Sequential Consistency

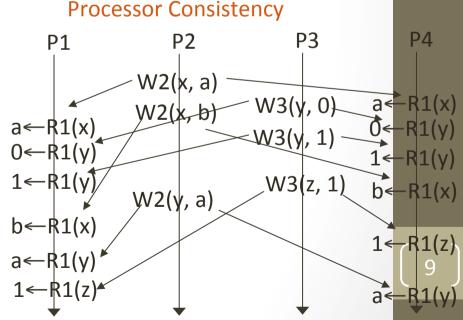
- Linearlizability: Operations of each individual process appear to all processes in the same order as they happen.
- Sequential Consistency: Operations of each individual process appear in the same order to all processes.



FIFO and Processor Consistency

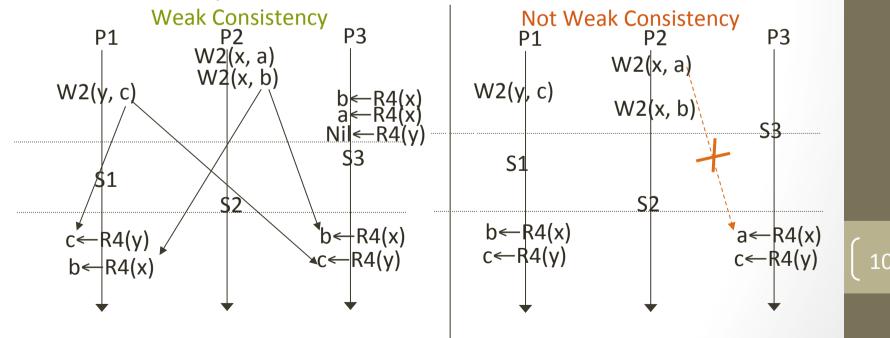
- **FIFO Consistency:** writes by a single process are visible to all other processes in the order in which they were issued.
- **Processor Consistency:** FIFO Consistency + all write to the same memory location must be visible in the same order.





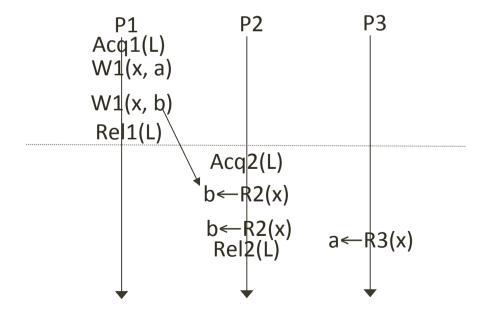
Weak Consistency

- Accesses to synchronization variables must obey sequential consistency.
- All previous writes must be completed before an access to a synchronization variable.
- All previous accesses to synchronization variables must be completed before access to non-synchronization variable.



Release Consistency

- Access to acquire and release variables obey processor consistency.
- Previous acquires requested by a process must be completed before the process performs a data access.
- All previous data accesses performed by a process must be completed before the process performs a release.

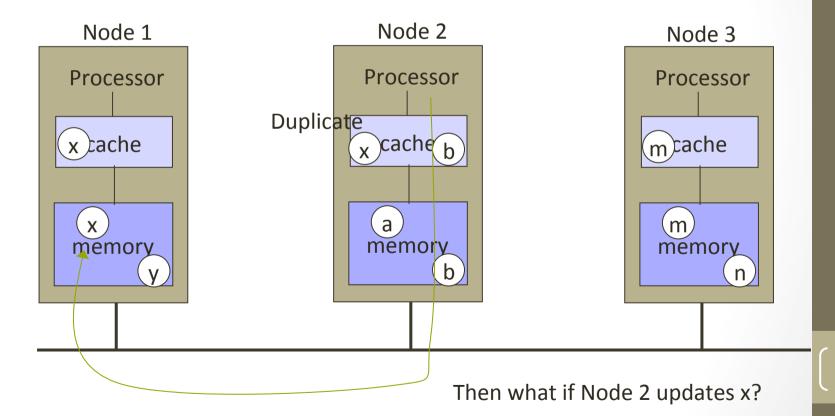


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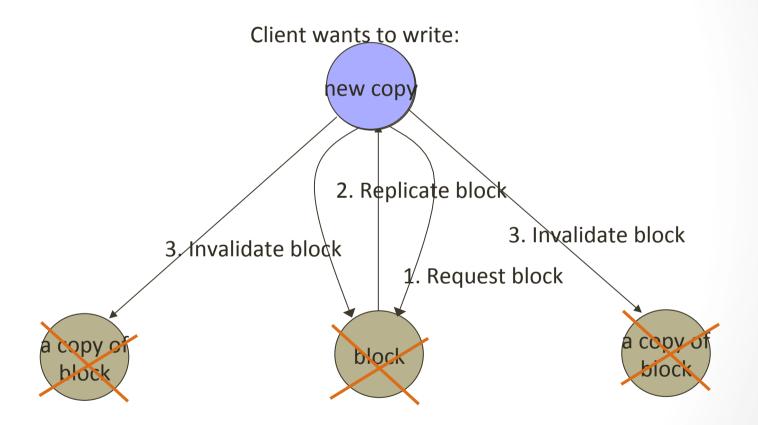
Release Consistency (Example)

```
Process 1:
acquireLock();  // enter \ critical \ section
a := a + 1;
b := b + 1;
releaseLock();  // leave \ critical \ section
Process 2:
acquireLock();  // enter \ critical \ section
print ("The \ values \ of \ a \ and \ b \ are: ", a, b);
releaseLock();  // leave \ critical \ section
```

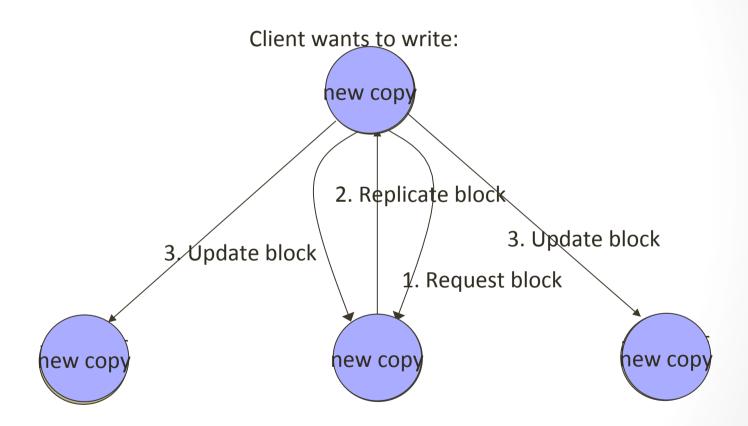
Replicated and Migrating Data Blocks



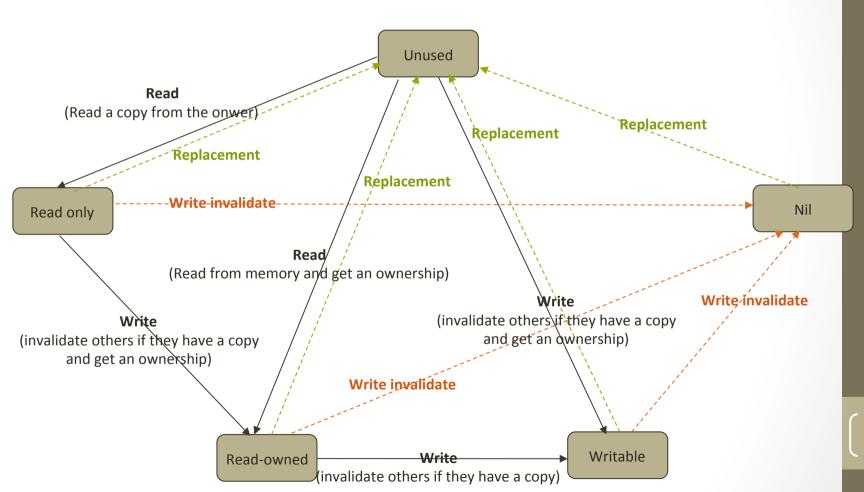
Write Invalidation



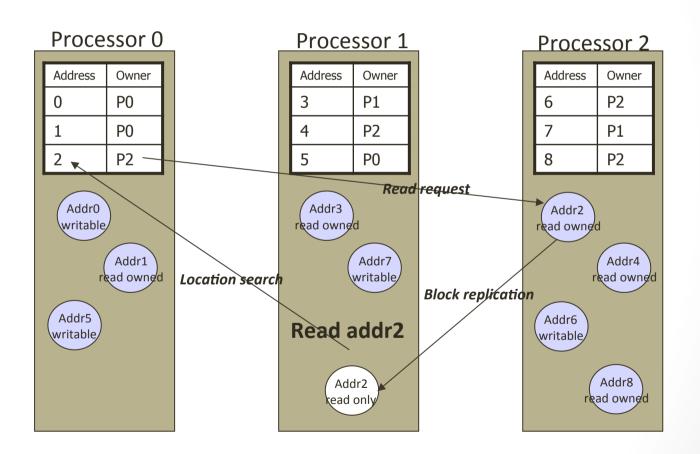
Implementing Sequential Consistency Write Update



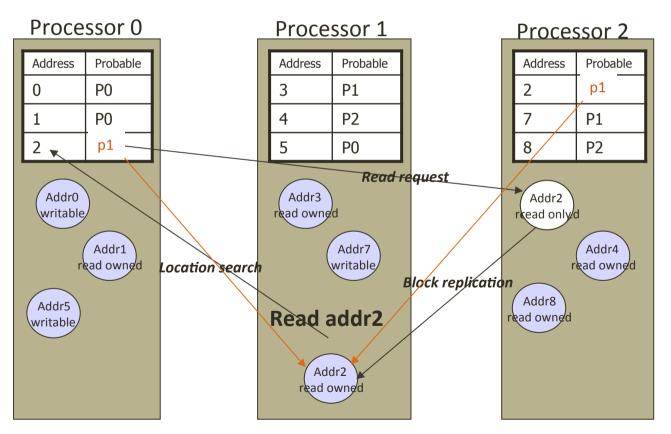
Read/Write Request



Locating Data – Fixed Distributed-Server Algorithms



Locating Data – Dynamic Distributed-Server Algorithms



- Breaking the chain of nodes:
 - When the node receives an invalidation
 - When the node relinquishes ownership
 - When the node forwards a fault request
- The node points to a new owner

Replacement Strategy

- Which block to replace
 - Non-usage based (e.g. FIFO)
 - Usage based (e.g. LRU)
 - Mixed of those (e.g. Ivy)
 - Unused/Nil: replaced with the highest priority
 - Read-only: the second priority
 - Read-owned: the third priority
 - Writable: the lowest priority and LRU used.
- Where to place a replaced block
 - Invalidating a block if other nodes have a copy.
 - Using secondary store
 - Using the memory space of other nodes

Thrashing

• Thrashing:

- Two or more processes try to write the same shared block.
- An owner keeps writing its block shared by two or more reader processes.
- The larger a block, the more chances of false sharing that causes thrashing.

Solutions:

- Allow a process to prevent a block from being accessed from the others, using a lock.
- Allow a process to hold a block for a certain amount of time.
- Apply a different coherence algorithm to each block.
- What do those solutions require users to do?
- Are there any perfect solutions?