

Computer aided design of thermoplastic profile forming tools

J. M. Nóbrega and O. S. Carneiro

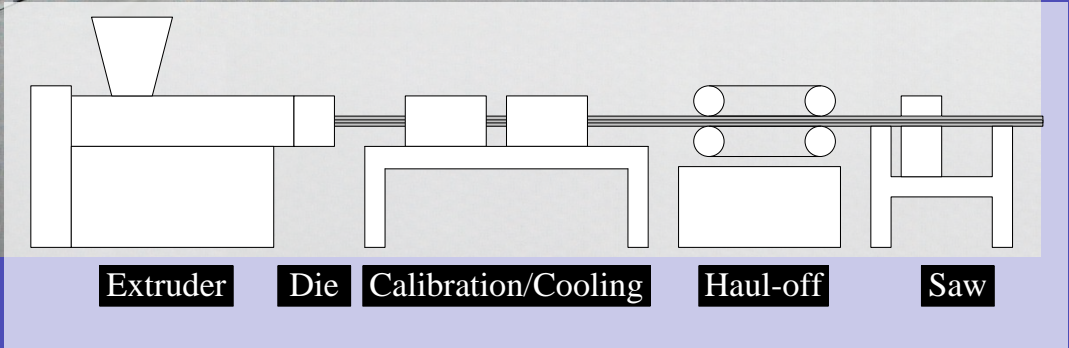
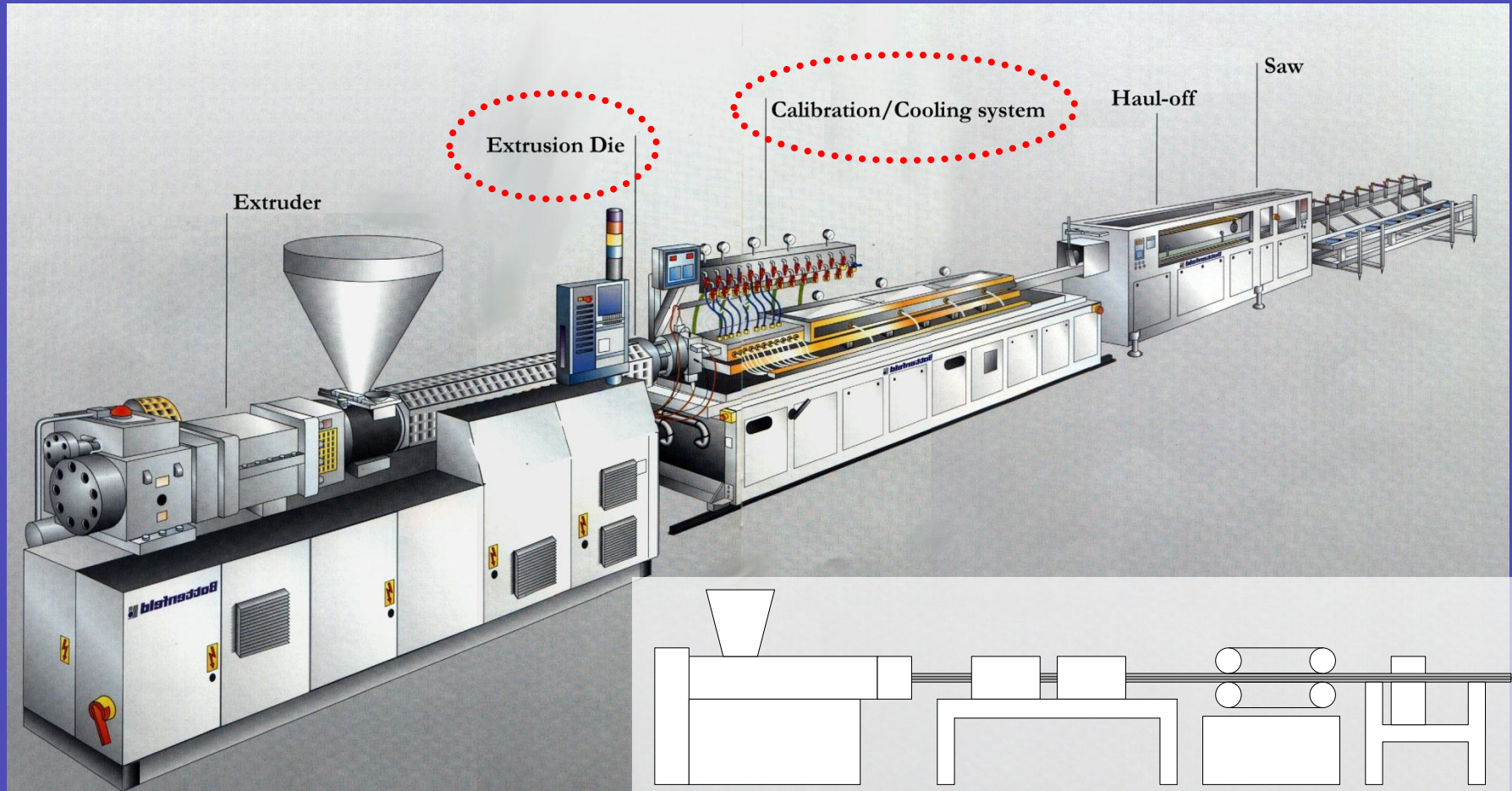


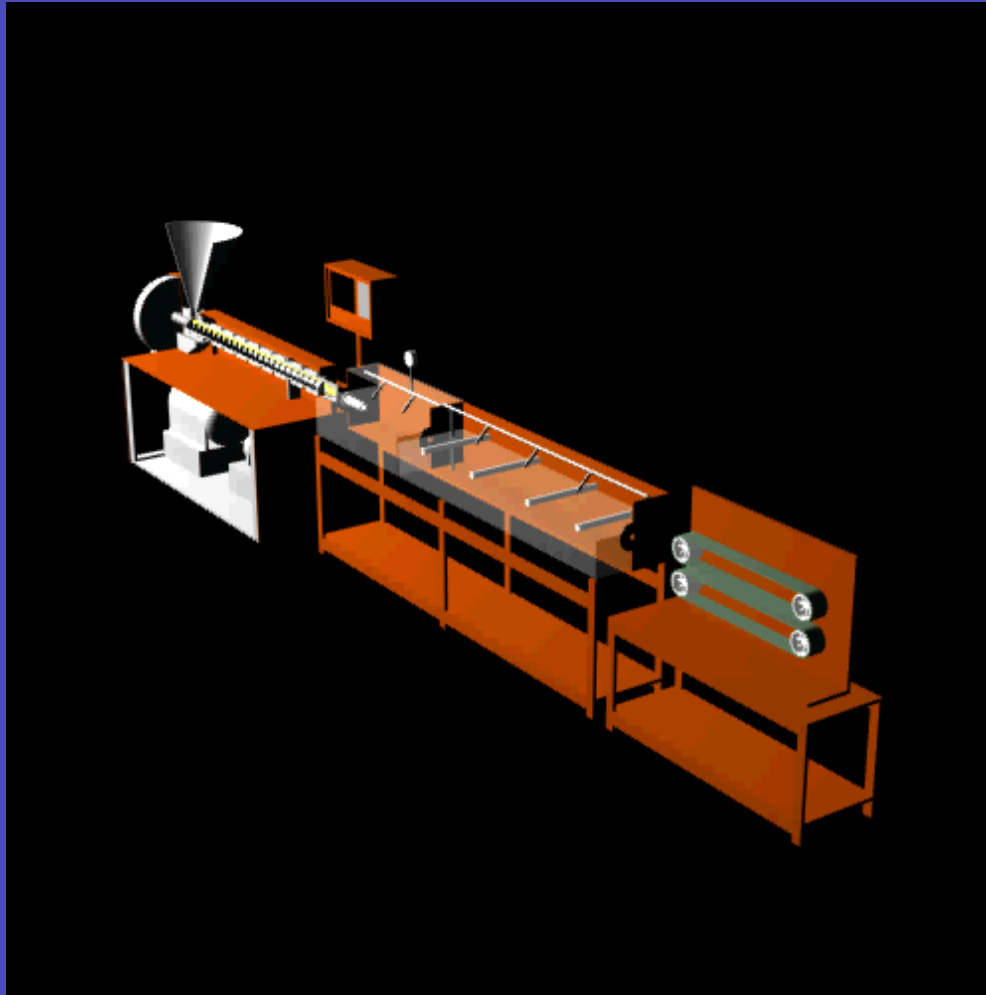
*I3N/IPC –Institute for Polymers and Composites
Department of Polymer Engineering
University of Minho
Portugal*

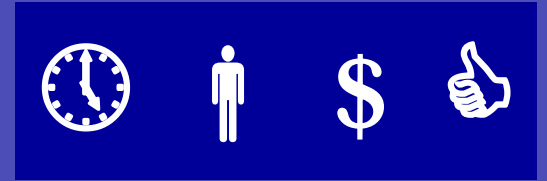


mnobrega@dep.uminho.pt / olgasc@dep.uminho.pt

Introduction - Profile Extrusion







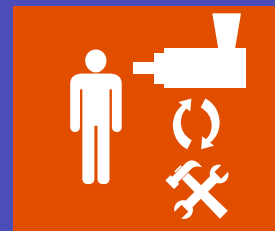
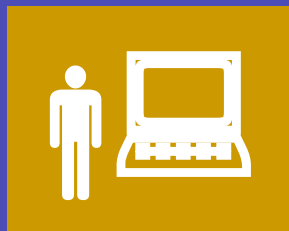
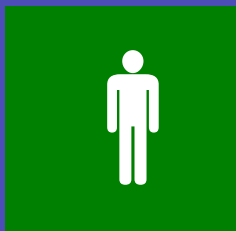
Traditional



Current



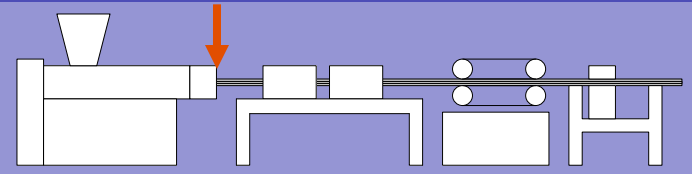
Under development





- **Extrusion Dies**
 - **Problem Statement**
 - **Flow Distribution Optimisation**
 - **Flow Balance Strategies**
 - **Optimisation**
 - **Length vs Thickness Optimisation**
 - **Conclusion**
- **Calibrators**
 - **Problem Statement**
 - **System Behaviour**
 - **Optimisation Methodology**
 - **Case Study**
 - **Conclusion**
- **Conclusion**
- **Ongoing Work**

Extrusion Dies – *Problem Statement*



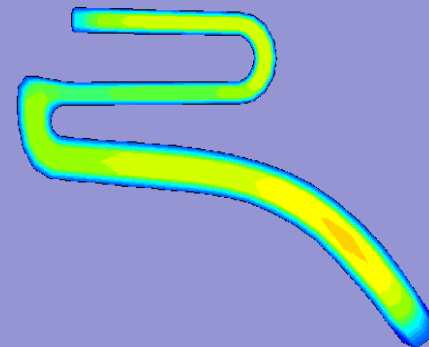
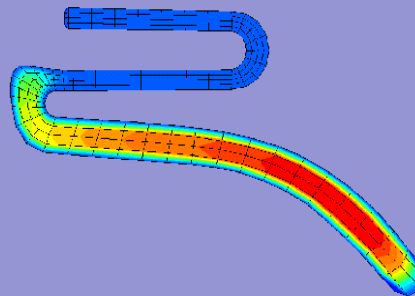
Unbalanced

Balanced

Extrusion run



**Numerical
Velocity contours**

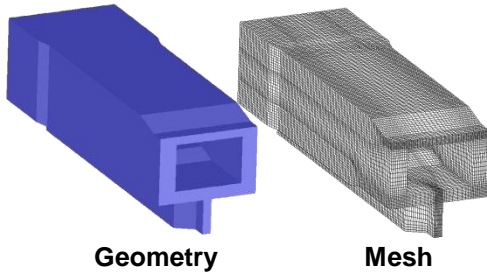


Extrusion Dies – Flow Distribution Optimisation



Trial Parameters

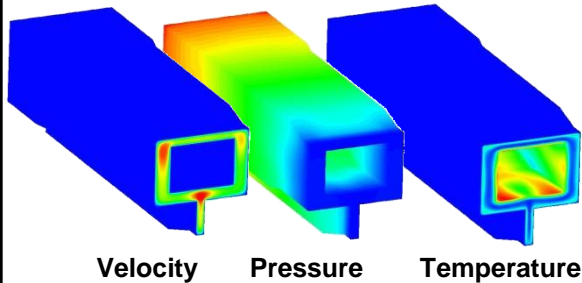
Pre-Processor



Geometry

Mesh

3D non-isothermal flow field calculation (FVM)



Velocity

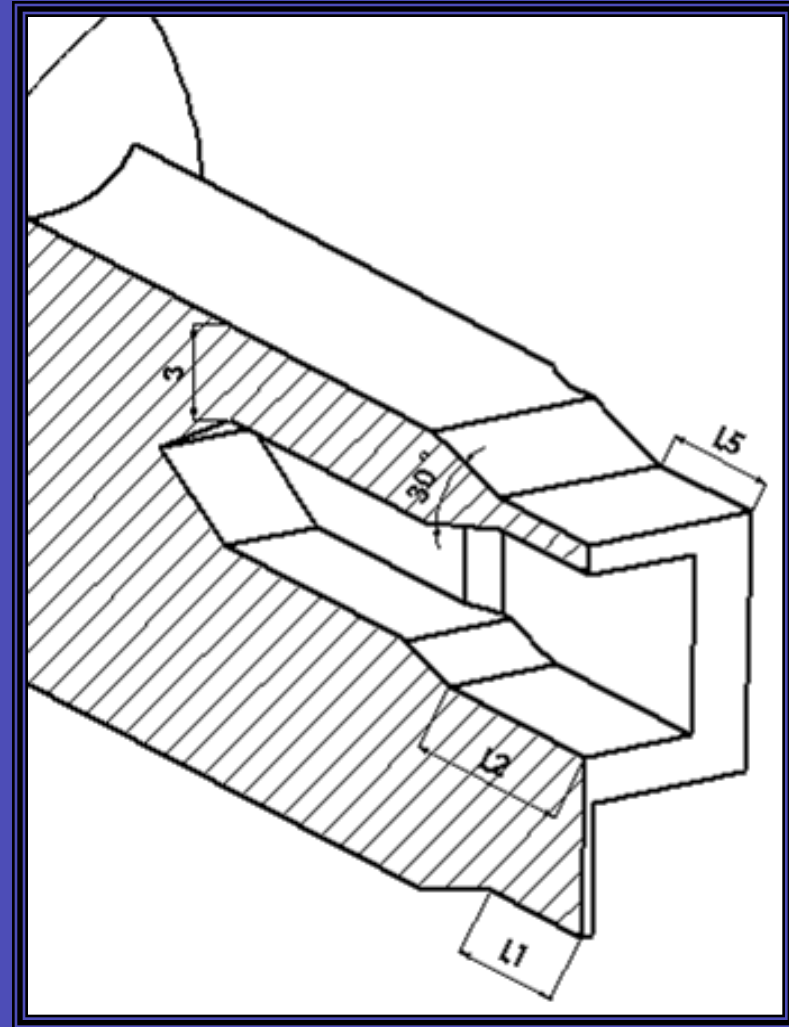
Pressure

Temperature

Performance Evaluation

$$F_{obj} = \sum_{i=1}^n \left\{ \left\{ \alpha \left(1 - \frac{V_i}{V_{obj,i}} \right)^2 + k(1-\alpha) \left[1 - \frac{(L/t)_i}{(L/t)_{min}} \right]^2 \right\} \frac{A_i}{A} \right\}$$

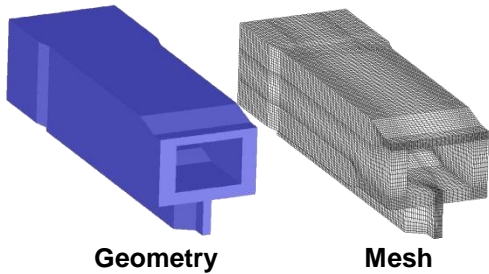
Modification of the controllable geometrical parameters until the optimum is reached





Trial Parameters

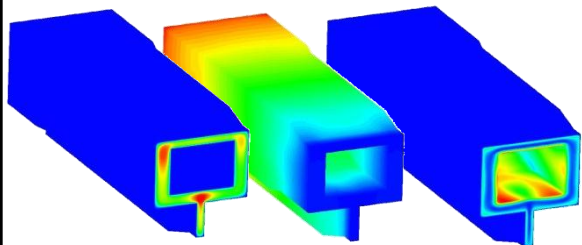
Pre-Processor



Geometry

Mesh

3D non-isothermal flow field calculation (FVM)



Velocity

Pressure

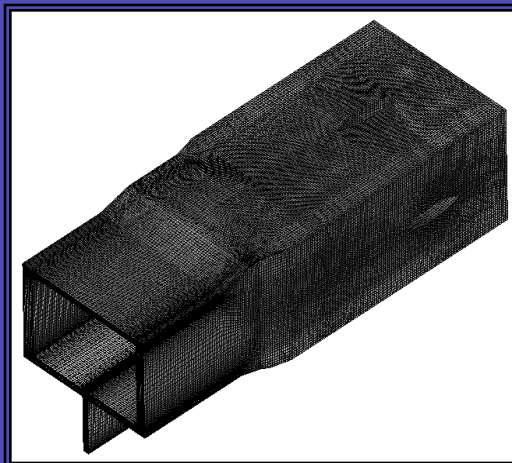
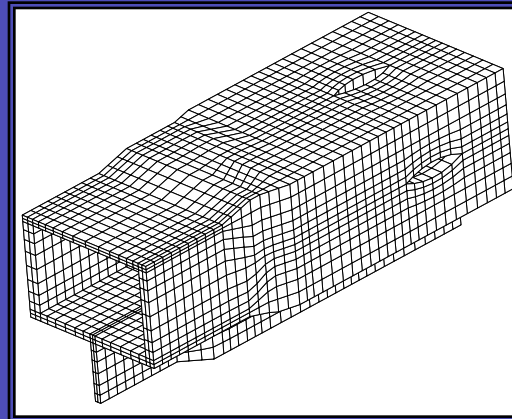
Temperature

Performance Evaluation

$$F_{obj} = \sum_{i=1}^n \left\{ \left\{ \alpha \left(1 - \frac{V_i}{V_{obj,i}} \right)^2 + k(1-\alpha) \left[1 - \frac{(L/t)_i}{(L/t)_{min}} \right]^2 \right\} \frac{A_i}{A} \right\}$$

Modification of the controllable geometrical parameters until the optimum is reached

Progressive mesh refinements



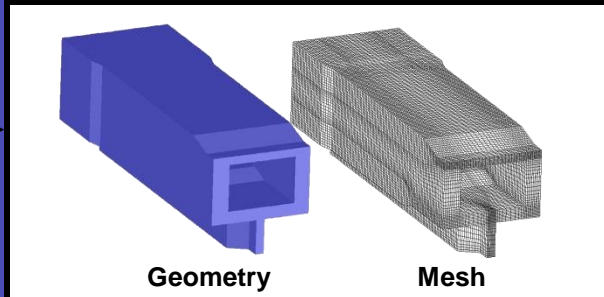
Cells along Thickness	Number of Cells	Time [h:m:s]
2	15 496	0:00:36
4	92 248	0:12:15
6	272 220	1:12:17
8	593 928	4:28:36
10	688 024	6:43:42

PIV / 2.4 GHz

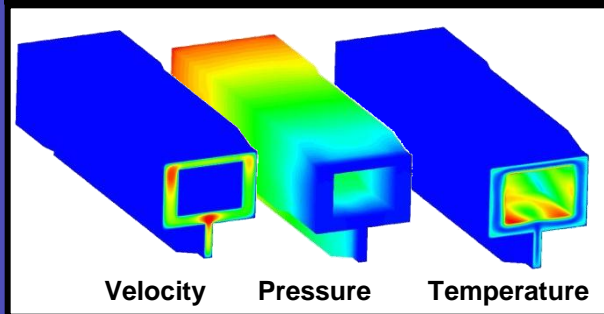


Trial Parameters

Pre-Processor



3D non-isothermal flow field calculation (FVM)



Performance Evaluation

$$F_{obj} = \sum_{i=1}^n \left\{ \left\{ \alpha \left(1 - \frac{V_i}{V_{obj,i}} \right)^2 + k(1-\alpha) \left[1 - \frac{(L/t)_i}{(L/t)_{min}} \right]^2 \right\} \frac{A_i}{A} \right\}$$

Modification of the controllable geometrical parameters until the optimum is reached

Equations to Solve

Conservation of mass:

$$\frac{\partial \rho u_j}{\partial x_j} = 0$$

Conservation of linear momentum:

$$\frac{\partial \rho u_i}{\partial t} + \frac{\partial \rho u_j u_i}{\partial x_j} = - \frac{\partial p}{\partial x_i} + \frac{\partial \tau_{ij}}{\partial x_j}$$

Conservation of energy:

$$\frac{\partial \rho c T}{\partial t} + \frac{\partial \rho c u_i T}{\partial x_i} = \frac{\partial}{\partial x_i} \left(k \frac{\partial T}{\partial x_i} \right) + \tau_{ij} \frac{\partial u_i}{\partial x_j}$$

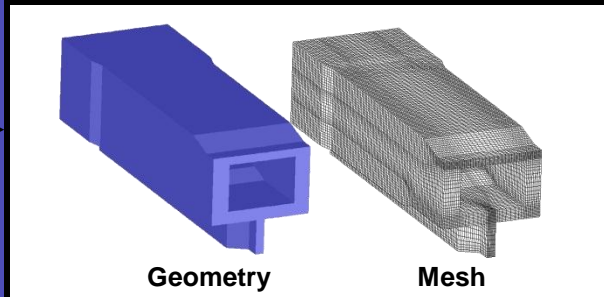
Constitutive equation (Gen. Newtonian):

$$\tau_{ij} = \eta(\dot{\gamma}) \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

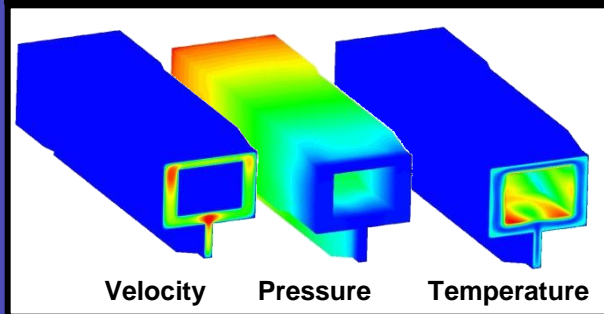


Trial Parameters

Pre-Processor



3D non-isothermal flow field calculation (FVM)



Performance Evaluation

$$F_{obj} = \sum_{i=1}^n \left\{ \left\{ \alpha \left(1 - \frac{V_i}{V_{obj,i}} \right)^2 + k(1-\alpha) \left[1 - \frac{(L/t)_i}{(L/t)_{min}} \right]^2 \right\} \frac{A_i}{A} \right\}$$

Modification of the controllable geometrical parameters until the optimum is reached

Equations to Solve

Conservation of mass:

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Conservation of linear momentum:

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Conservation of energy:

$$\frac{\partial \rho c T}{\partial t} + \frac{\partial \rho c u_i T}{\partial x_i} = \frac{\partial}{\partial x_i} \left(k \frac{\partial T}{\partial x_i} \right) + \tau_{ij} \frac{\partial u_i}{\partial x_j}$$

Constitutive equation (viscoelastic):

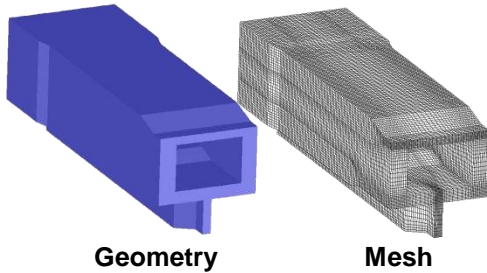
$$\tau_{ij} + \lambda \left(\frac{\partial \tau_{ij}}{\partial t} + \frac{\partial (u_k \tau_{ij})}{\partial x_k} \right) = \eta_p \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) + \lambda \left(\tau_{jk} \frac{\partial u_i}{\partial x_k} + \tau_{ik} \frac{\partial u_j}{\partial x_k} \right)$$

Extrusion Dies – Flow Distribution Optimisation



Trial Parameters

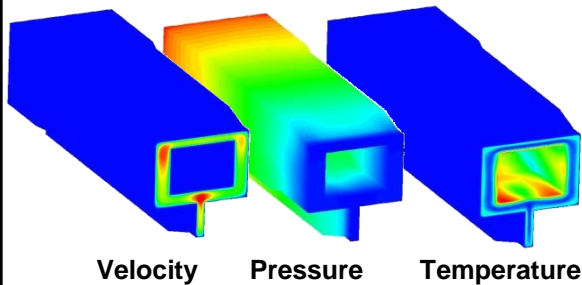
Pre-Processor



Geometry

Mesh

3D non-isothermal flow field calculation (FVM)



Velocity

Pressure

Temperature

Performance Evaluation

$$F_{obj} = \sum_{i=1}^n \left\{ \left\{ \alpha \left(1 - \frac{V_i}{V_{obj,i}} \right)^2 + k(1-\alpha) \left[1 - \frac{(L/t)_i}{(L/t)_{min}} \right]^2 \right\} \frac{A_i}{A} \right\}$$

Modification of the controllable geometrical parameters until the optimum is reached

Objective Function

Area Weighting

$$F_{obj} = \sum_{i=1}^n \left\{ \left\{ \alpha \left(1 - \frac{V_i}{V_{obj,i}} \right)^2 + k(1-\alpha) \left[1 - \frac{(L/t)_i}{(L/t)_{min}} \right]^2 \right\} \frac{A_i}{A} \right\}$$

Flow Balance

Admissible L/t value

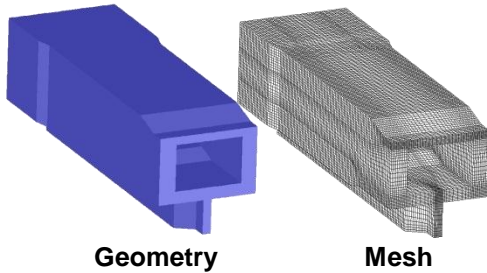
Area Weighting

Extrusion Dies – Flow Distribution Optimisation

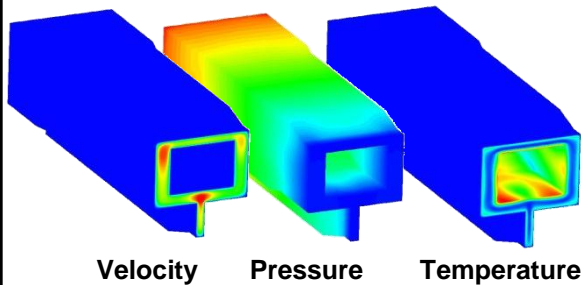


Trial Parameters

Pre-Processor



3D non-isothermal flow field calculation (FVM)



Performance Evaluation

$$F_{obj} = \sum_{i=1}^n \left\{ \left\{ \alpha \left(1 - \frac{V_i}{V_{obj,i}} \right)^2 + k(1-\alpha) \left[1 - \frac{(L/t)_i}{(L/t)_{min}} \right]^2 \right\} \frac{A_i}{A} \right\}$$

Modification of the controllable geometrical parameters until the optimum is reached

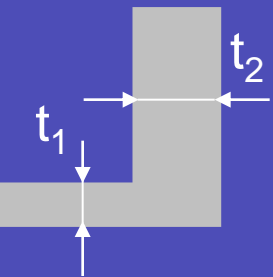
SIMPLEX Method (SM)

Experimental Method (EM)

Extrusion Dies – Flow Balance Strategies



Required Profile

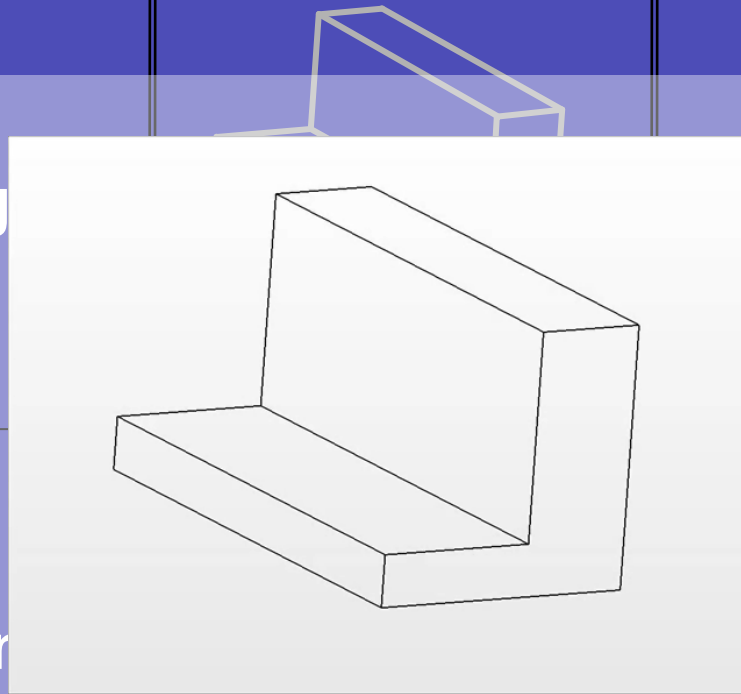


Optimised Variable

Length

Thickness

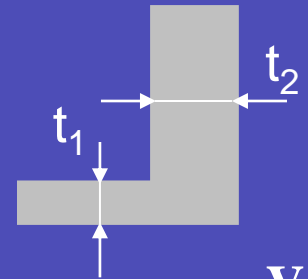
Die Flow Channel



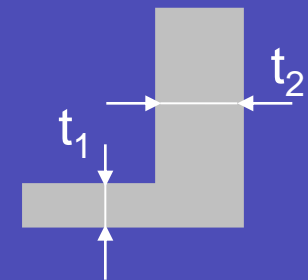
Haul-off Speed

V_3

Final Profile



$$\frac{V_3}{V_1} = \frac{V_3}{V_2}$$



$$\frac{V_3}{V_1} \neq \frac{V_3}{V_2}$$



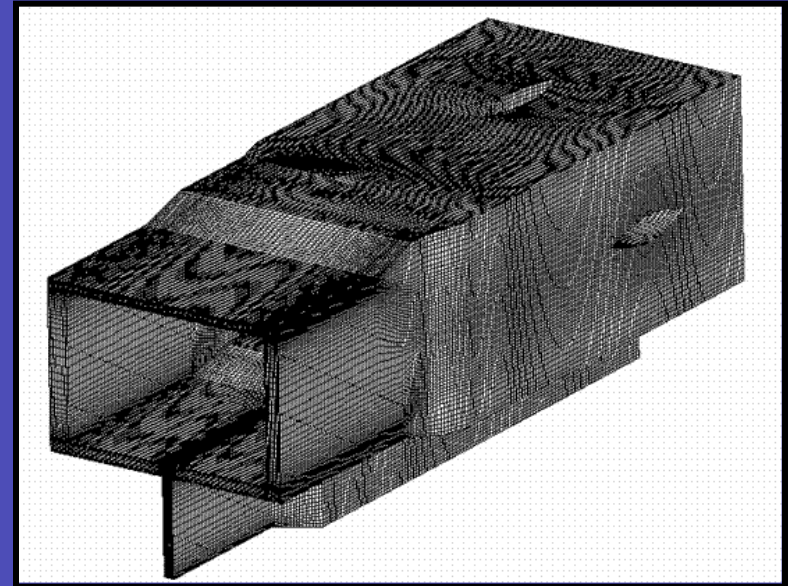


Constitutive equation

$$\eta(\dot{\gamma}, T) = F(\dot{\gamma} \times H(T)) H(T)$$

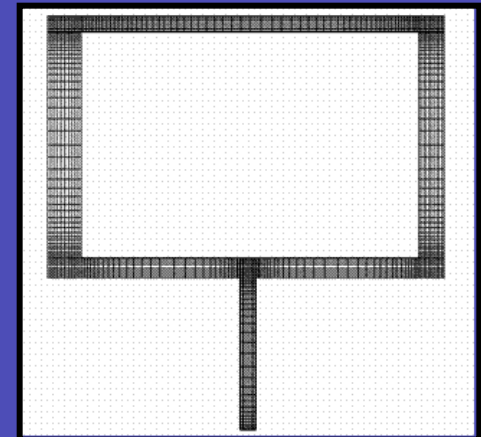
$$F(\dot{\gamma}) = \eta_{\infty} + \frac{\eta_0 - \eta_{\infty}}{(1 + (\lambda \dot{\gamma})^2)^{\frac{1-n}{2}}} \quad H(T) = \exp\left[\alpha \left(\frac{1}{T} - \frac{1}{T_a}\right)\right]$$

Mesh



Operating and thermal boundary conditions

Flow rate	20 kg/h
Melt inlet temperature	230 °C
Outer die walls temperature	230 °C
Inner (mandrel) die walls	Adiabatic





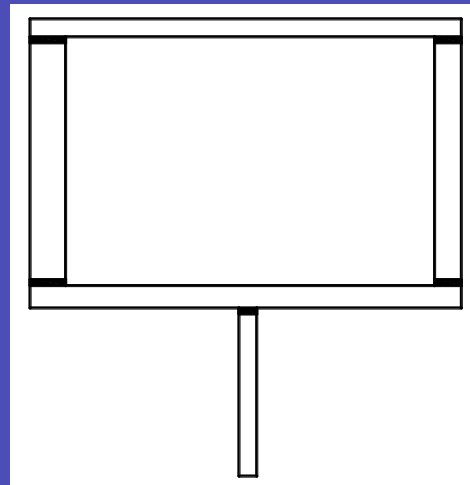
DieINI – Initial trial

Optimizations performed

DieL – Length optimisation

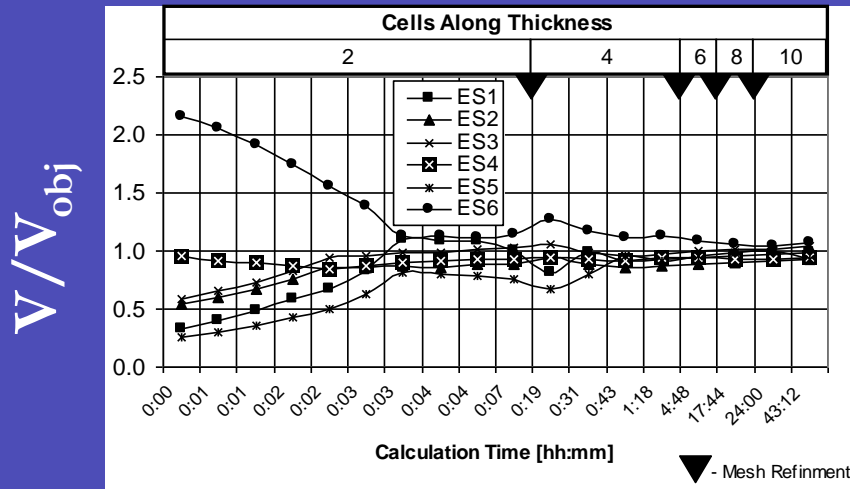
DieT – Thickness optimisation

DieLS – Length optimisation + Flow separators

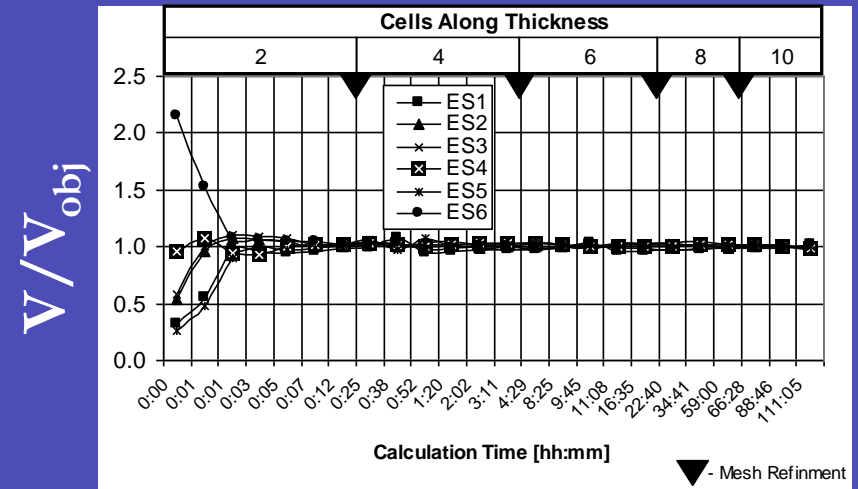




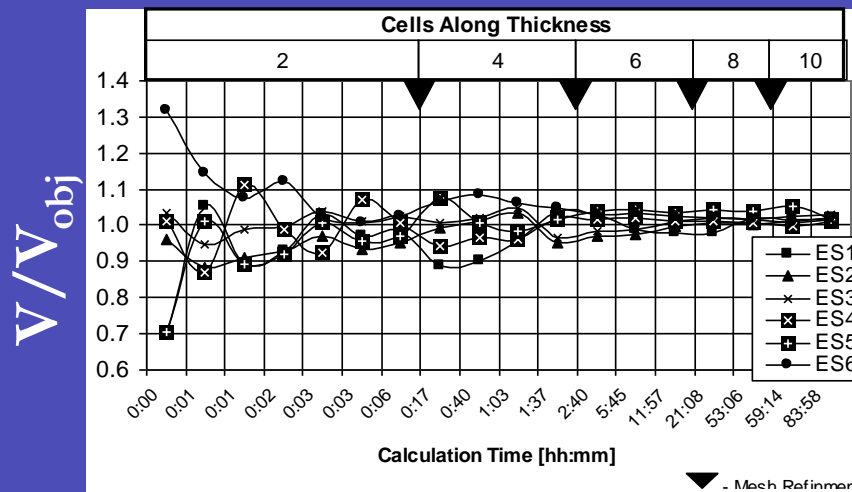
DieL



DieT

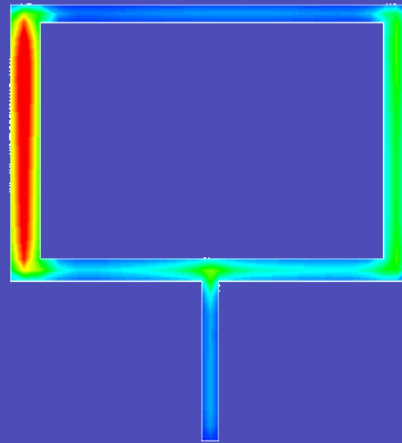


DieLS

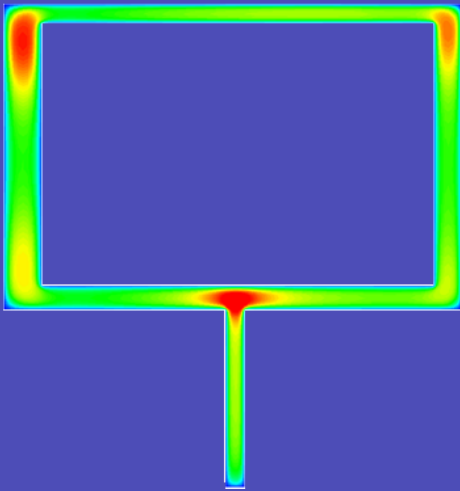




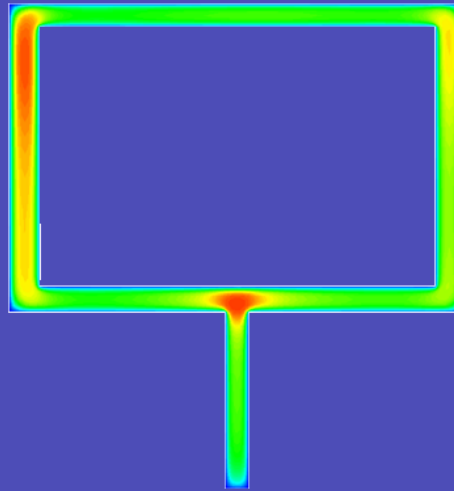
DieIni



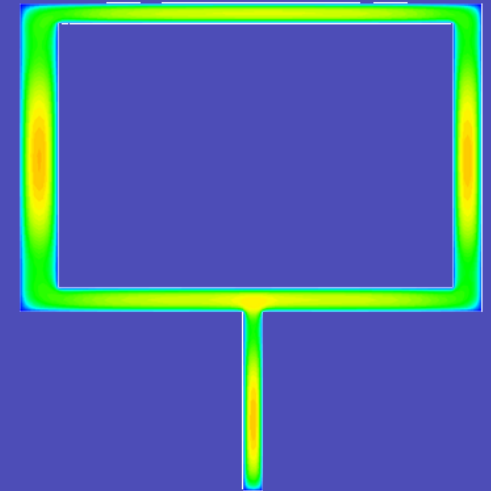
DieL



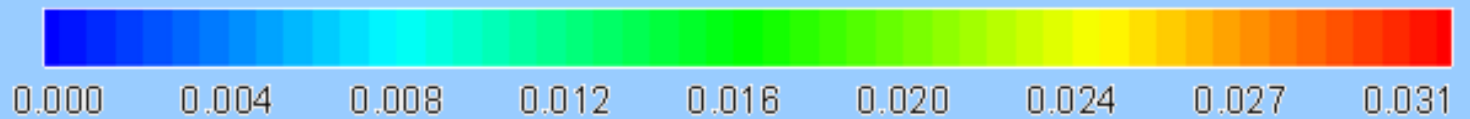
DieT



DieLS



Velocity [m/s]





DieIni



DieL



DieT

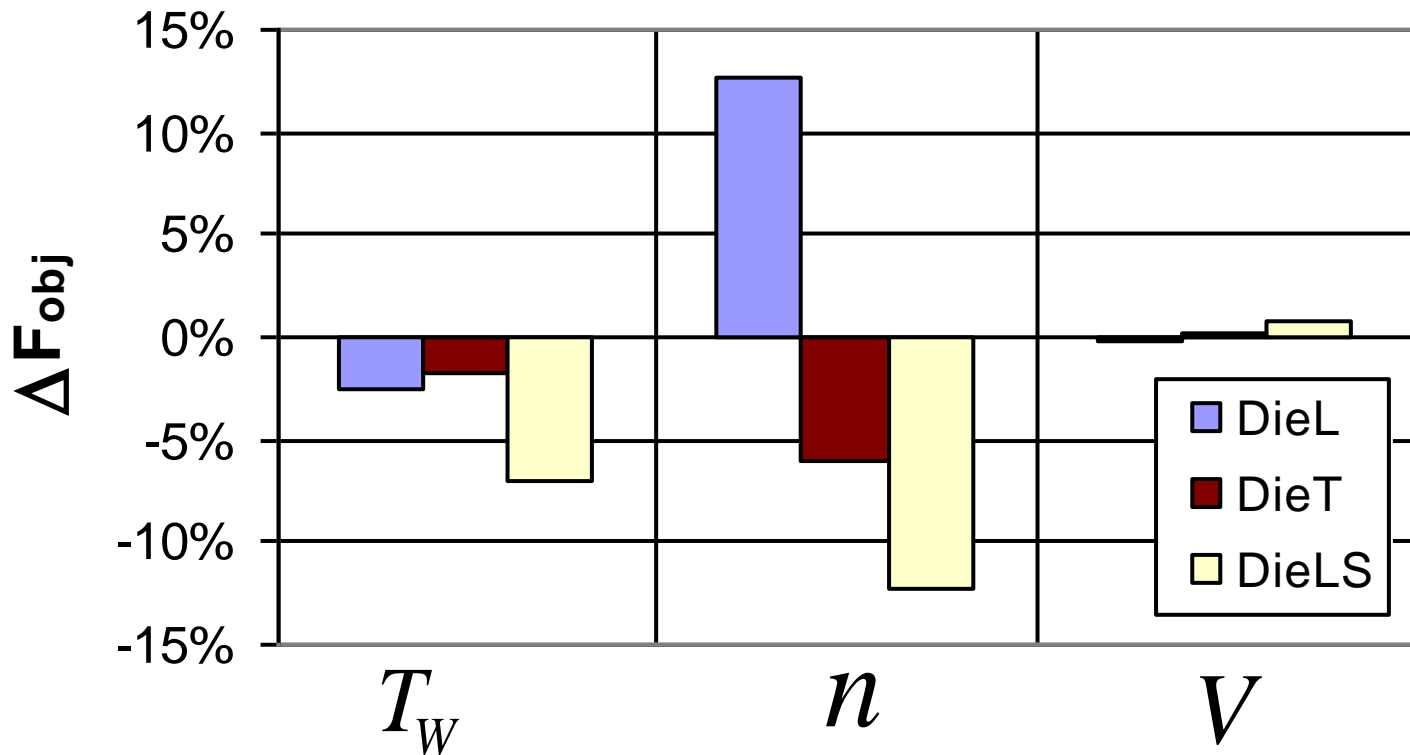


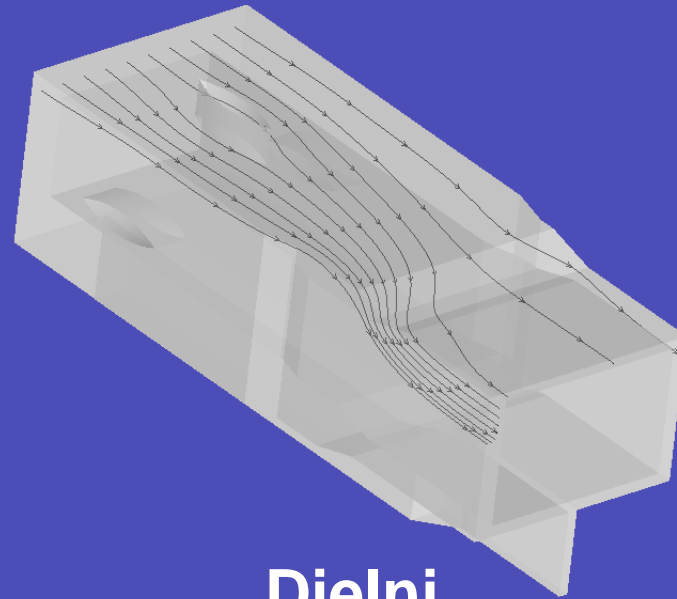


The factors considered can be divided in two different groups:

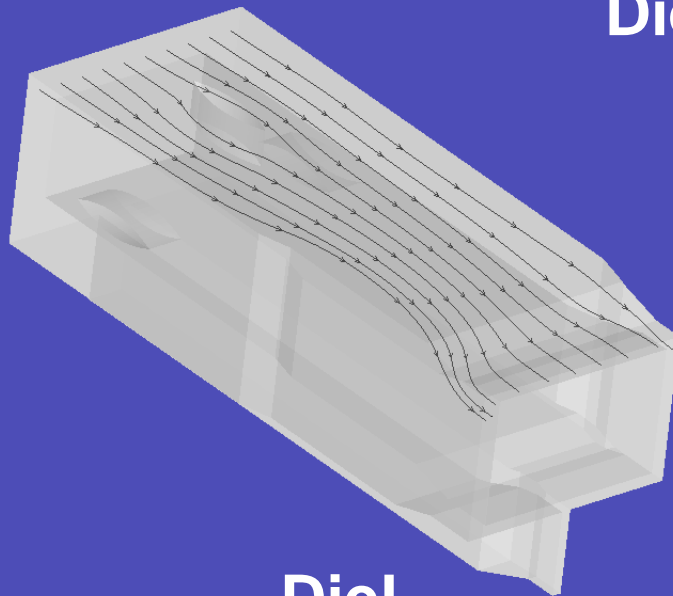
- i) **processing conditions:** V , T_w
- ii) **melt rheological properties:** n

The experiments (simulations) performed were defined by a statistics Taguchi technique, considering three levels for each factor

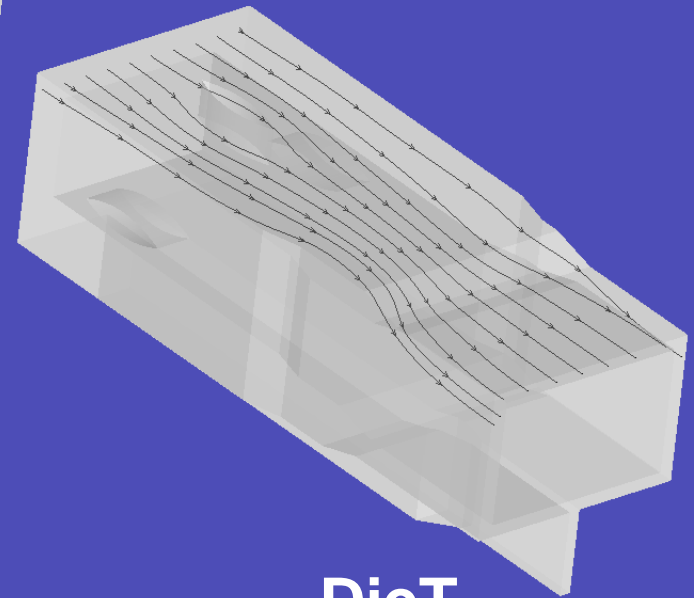




DieIni



DieL



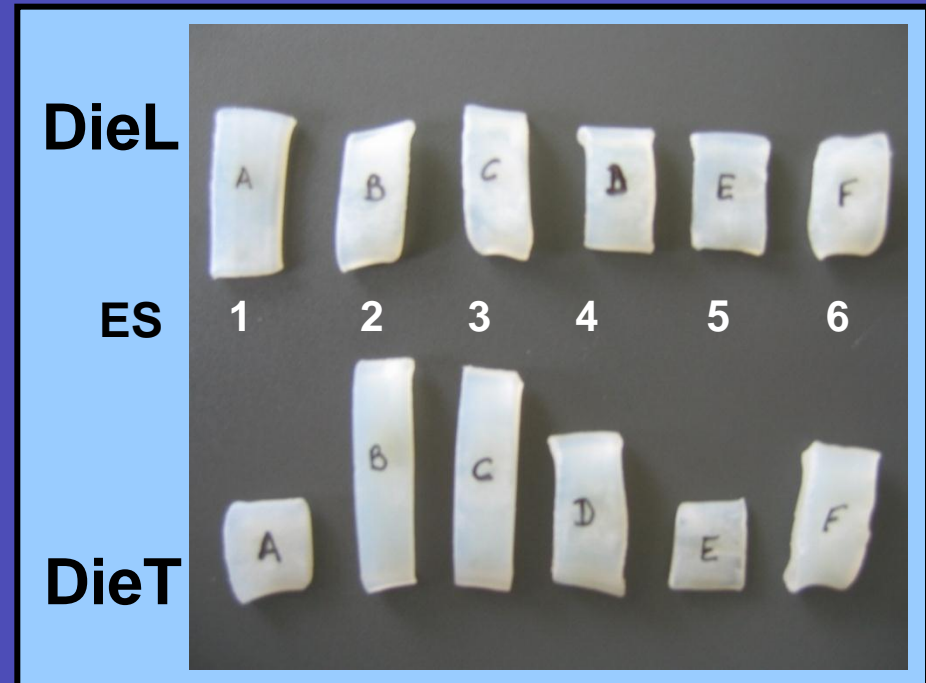
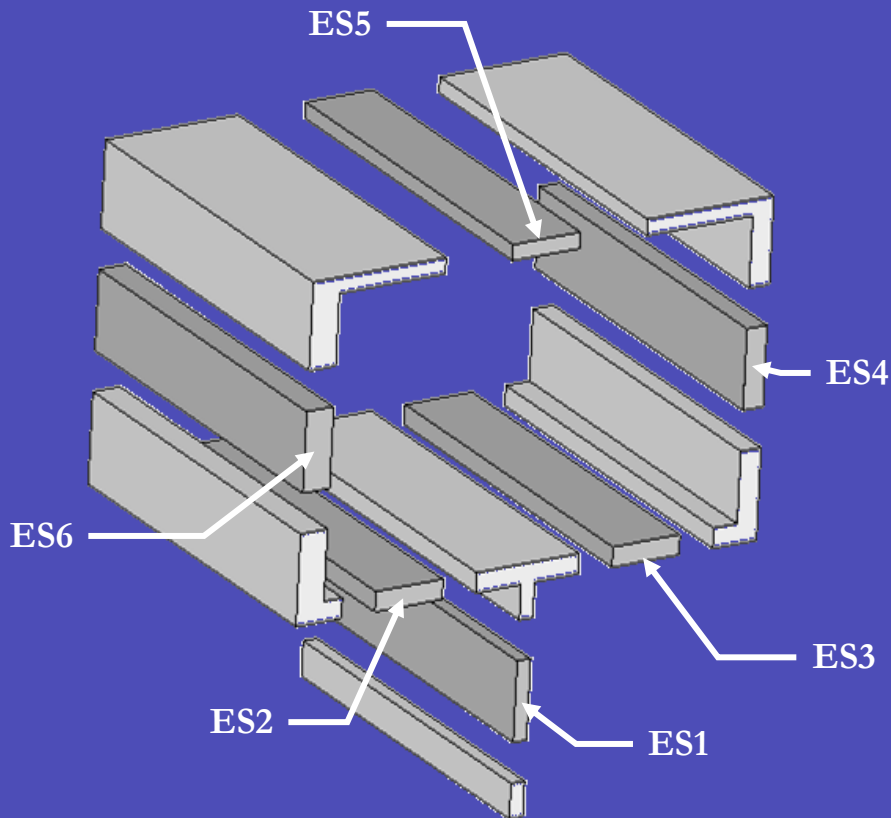
DieT

Extrusion Dies - Length vs Thickness Optimisation



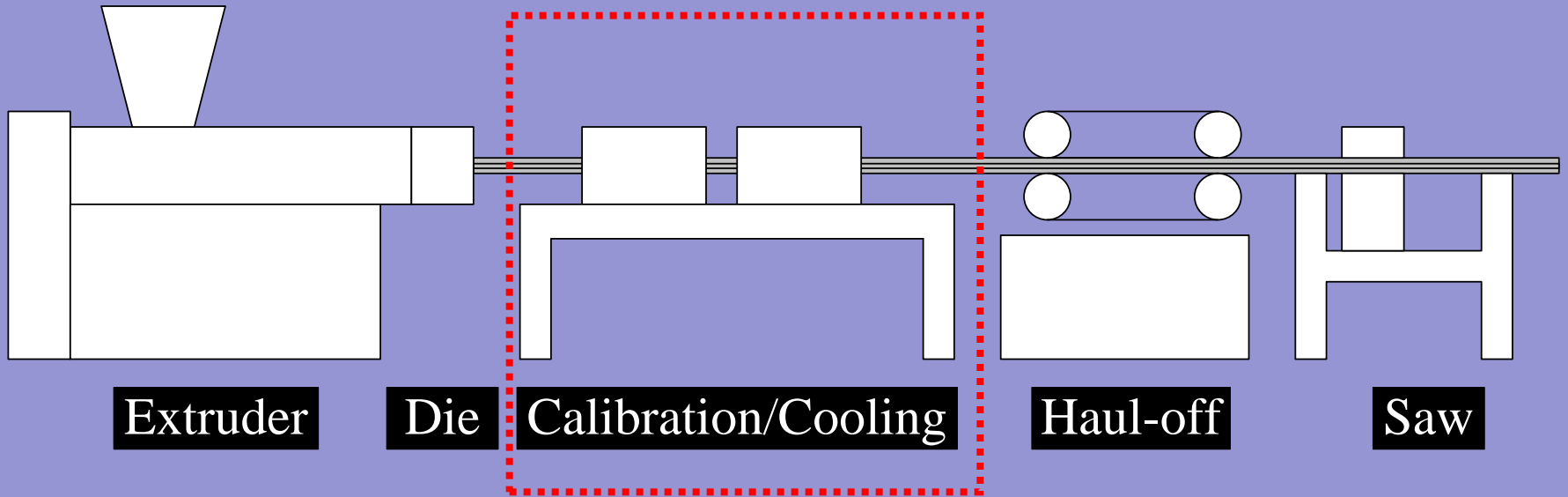
$$\text{Ratio } \bar{V}_{\max} / \bar{V}$$

Extrusion Die	ES1	ES2	ES3	ES4	ES5	ES6
DieINI	6.20	3.72	3.39	2.18	7.46	1.00
DieL	1.08	1.15	1.03	1.12	1.15	1.00
DieT	1.68	1.38	1.33	1.24	1.56	1.00

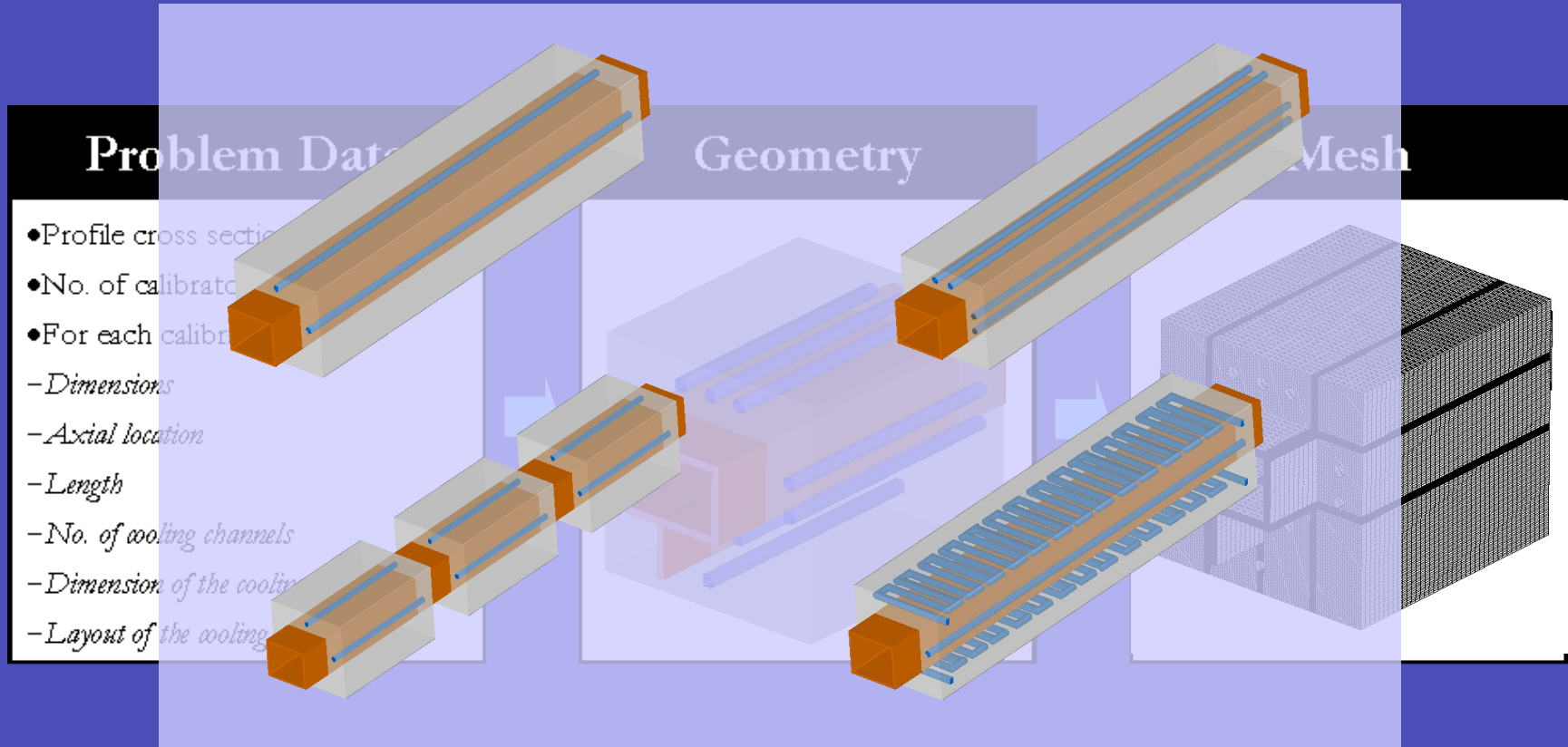


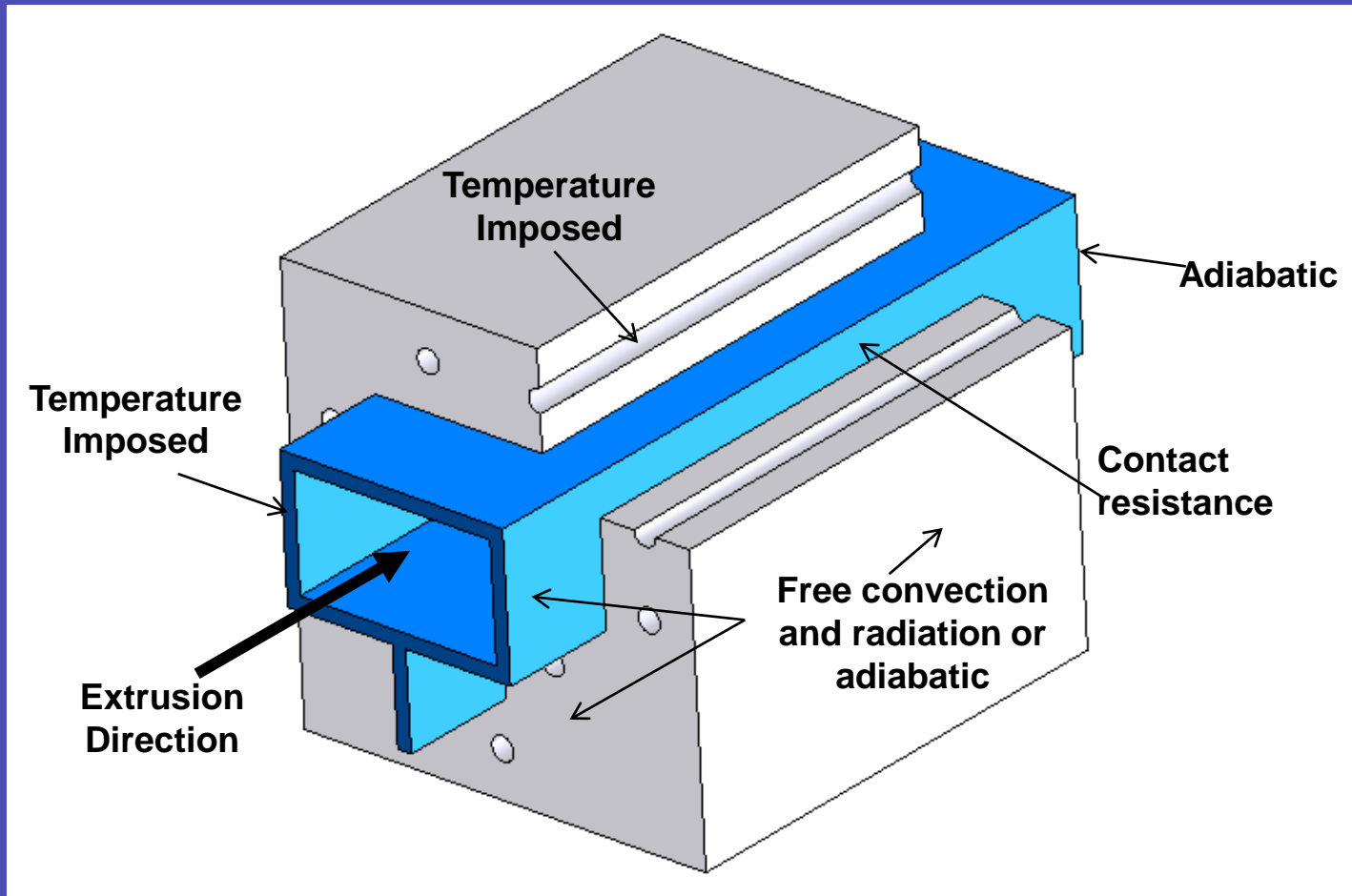


- *Length control* is difficult to apply in geometries with different flow restrictions and leads to dies with higher sensitivity to processing conditions than thickness control;
- *Flow separators* had a positive effect in the flow distribution but affect negatively in the die sensitivity;
- *Thickness optimised dies* produce extrudates that have higher propensity to distort.



$$\bar{T} < T_s \quad \downarrow \quad \sigma_T$$







Polymer

$$\frac{\partial}{\partial x} \left(k_p \frac{\partial T_p}{\partial x} \right) + \frac{\partial}{\partial y} \left(k_p \frac{\partial T_p}{\partial y} \right) + \frac{\partial}{\partial z} \left(k_p \frac{\partial T_p}{\partial z} \right) - \rho_p c_p \frac{\partial}{\partial z} (w T_p) = 0$$

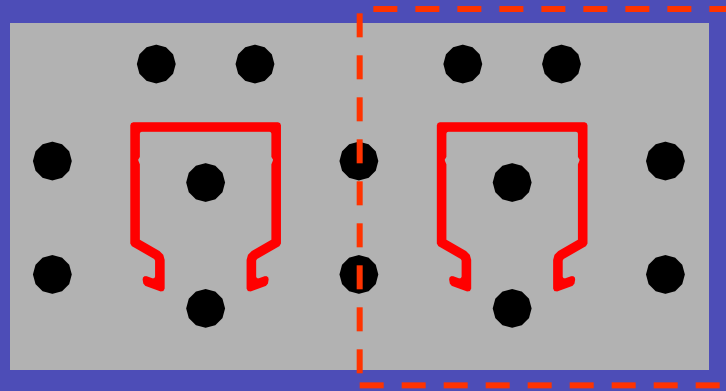
Calibrator

$$\frac{\partial}{\partial x} \left(k_c \frac{\partial T_c}{\partial x} \right) + \frac{\partial}{\partial y} \left(k_c \frac{\partial T_c}{\partial y} \right) + \frac{\partial}{\partial z} \left(k_c \frac{\partial T_c}{\partial z} \right) = 0$$

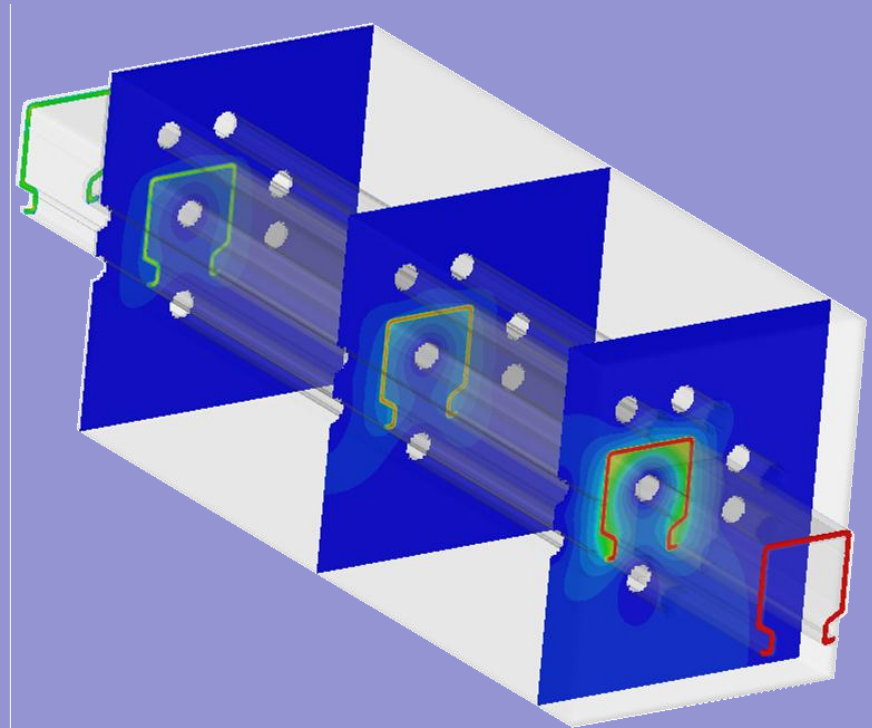
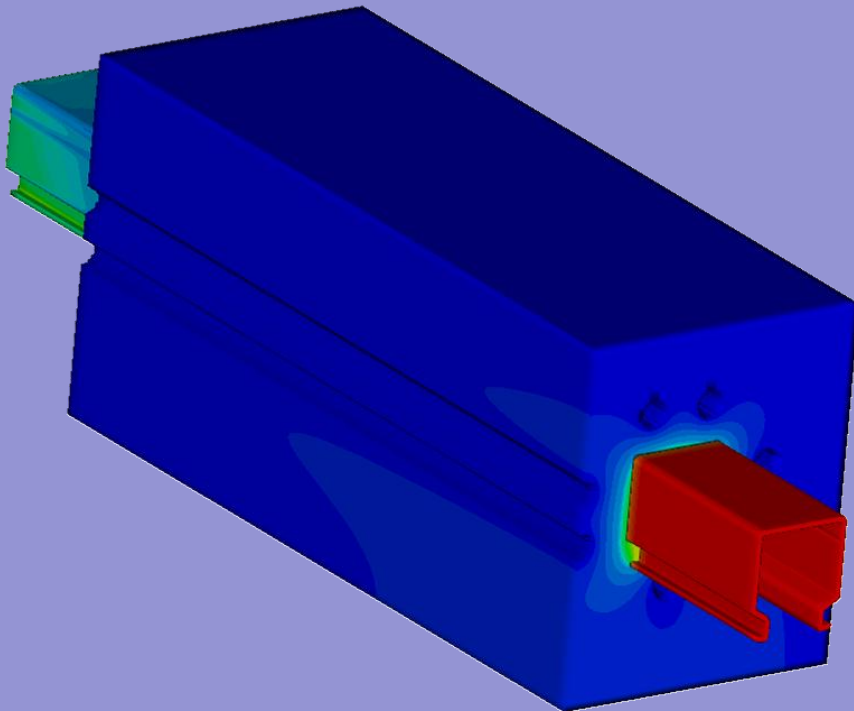
Polymer-calibrator interface

Contact Resistance

$$k_c \left(\frac{\partial T_c}{\partial n} \right)_{\text{interface}} = -k_p \left(\frac{\partial T_p}{\partial n} \right)_{\text{interface}} = h_i (T_p - T_c)_{\text{interface}}$$



3D Temperature field calculation (FVM)





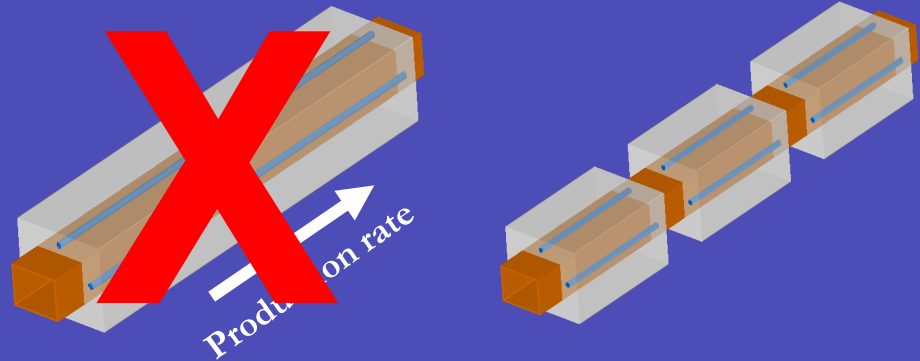
Influence of boundary conditions, process and geometrical parameters on the system performance (in terms of average temperature and temperature uniformity)

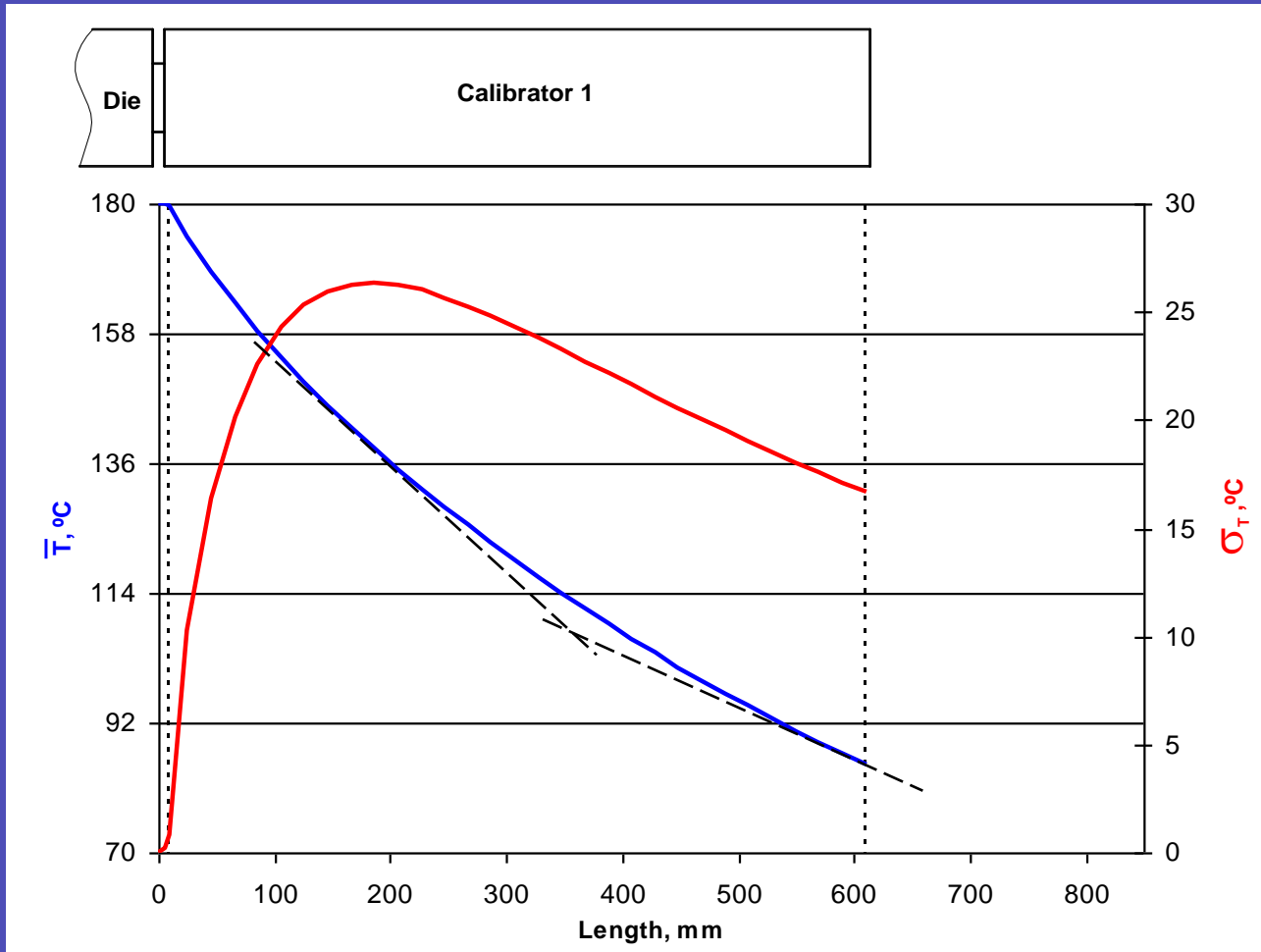
Conclusion:

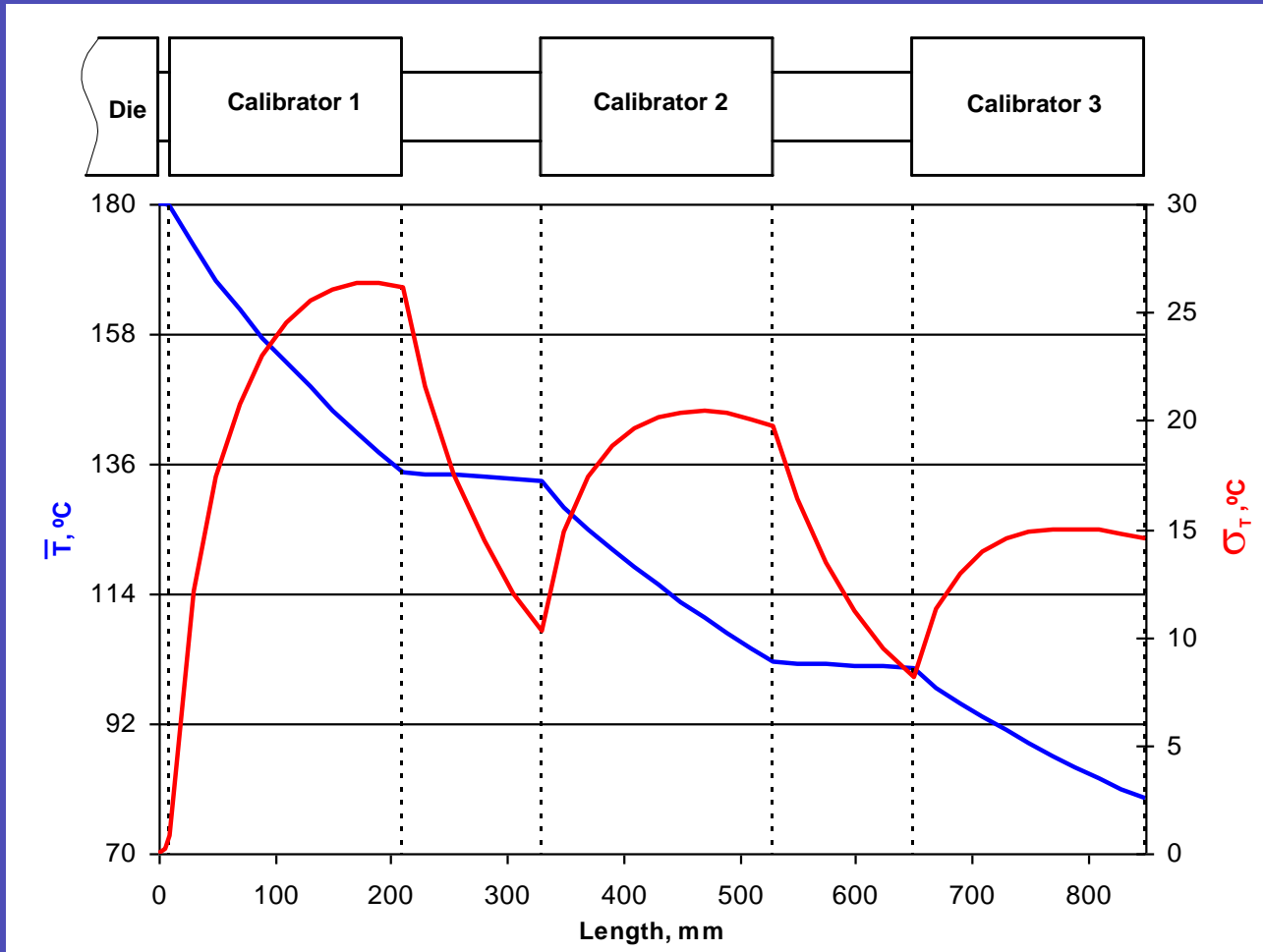
In general

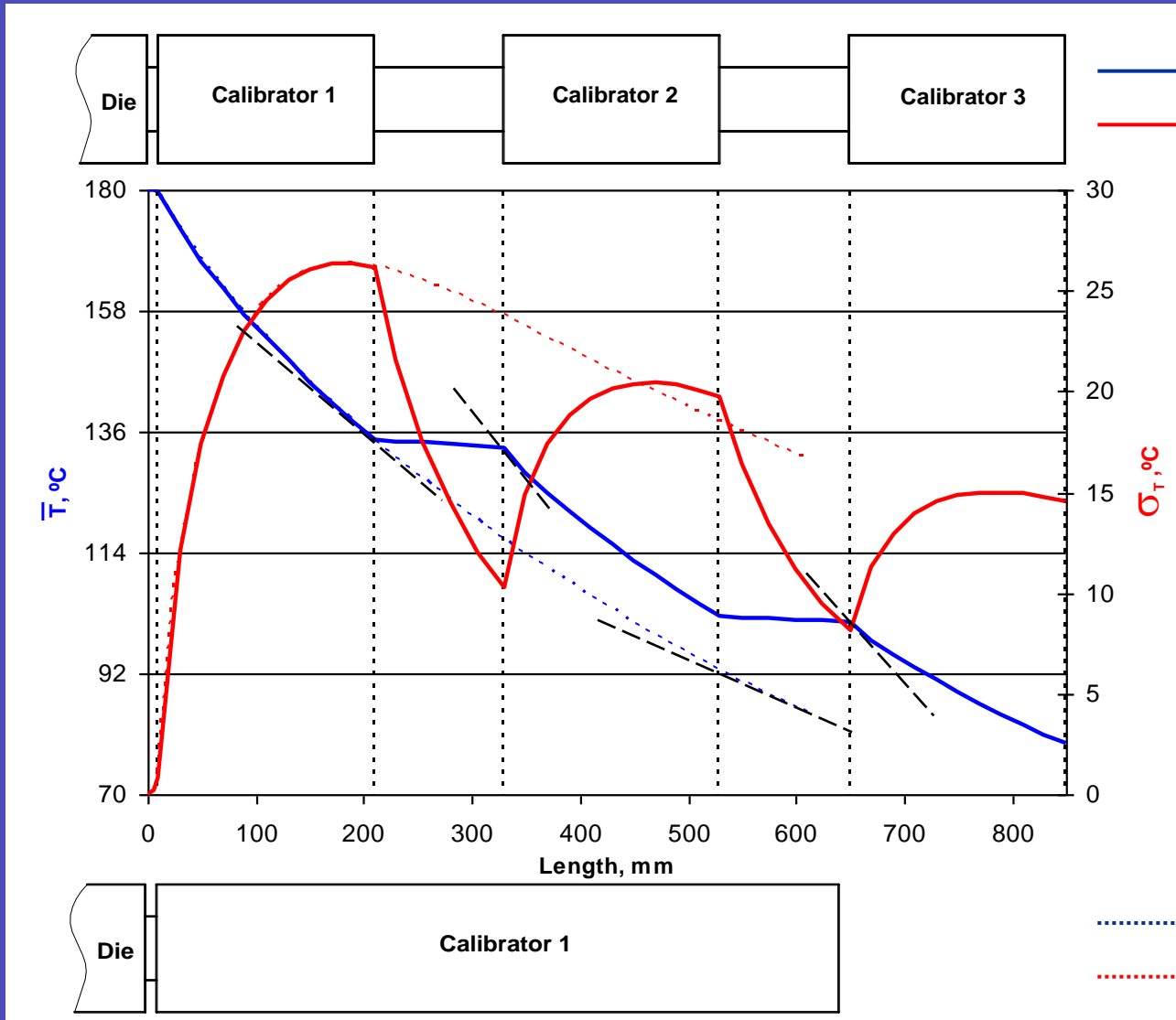
Exceptions

$$\downarrow \bar{T} \Rightarrow \uparrow \sigma_T$$



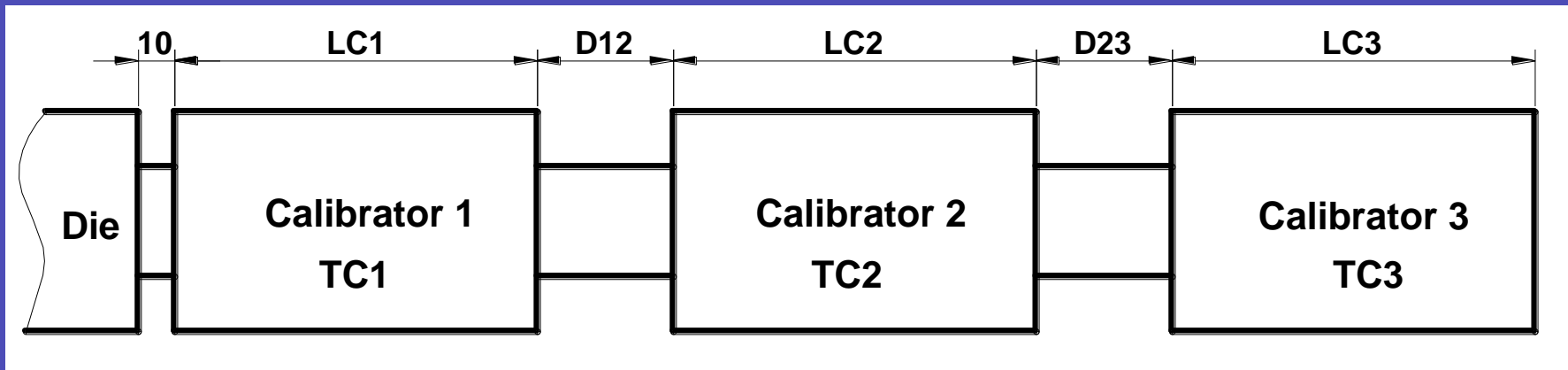






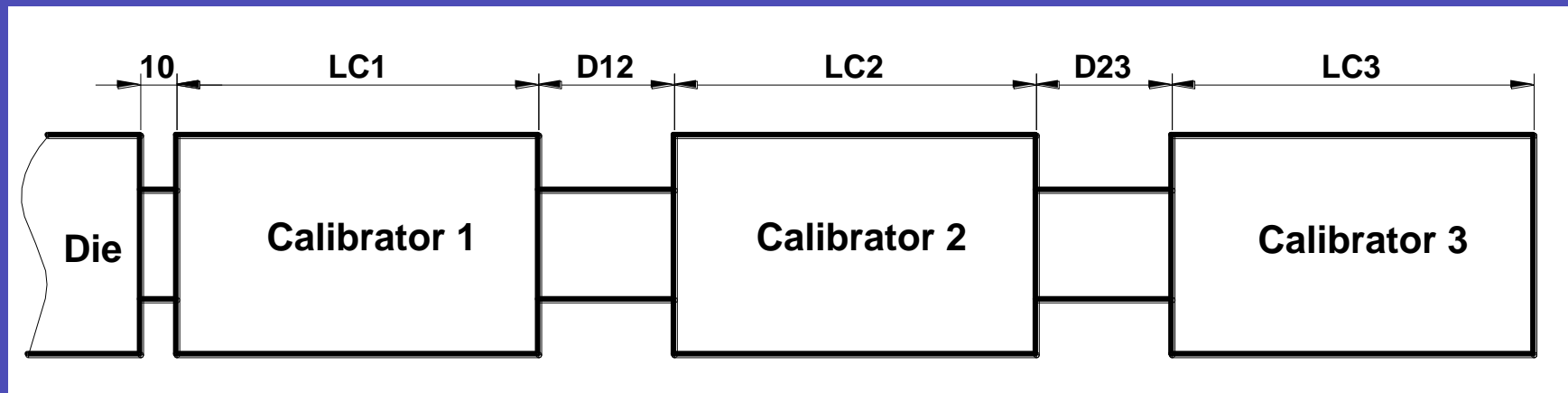


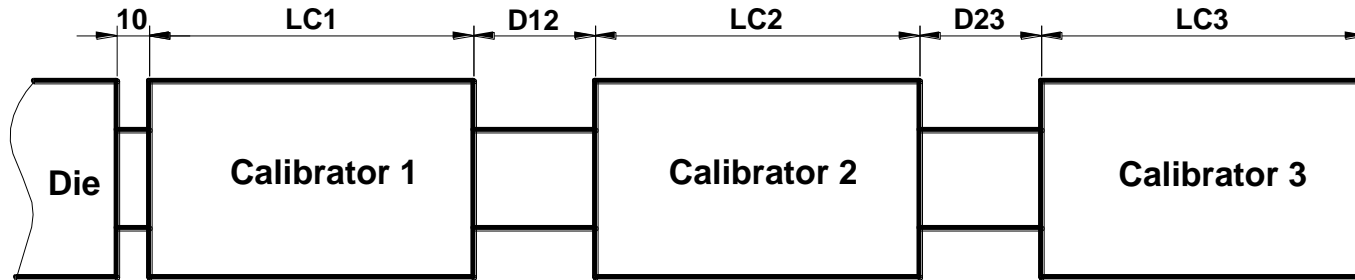
Influence of the **cooling units** and **annealing zones** lengths and **cooling fluid temperature** on the **system performance**





Influence of Length Distribution LC_i and D_{ij}

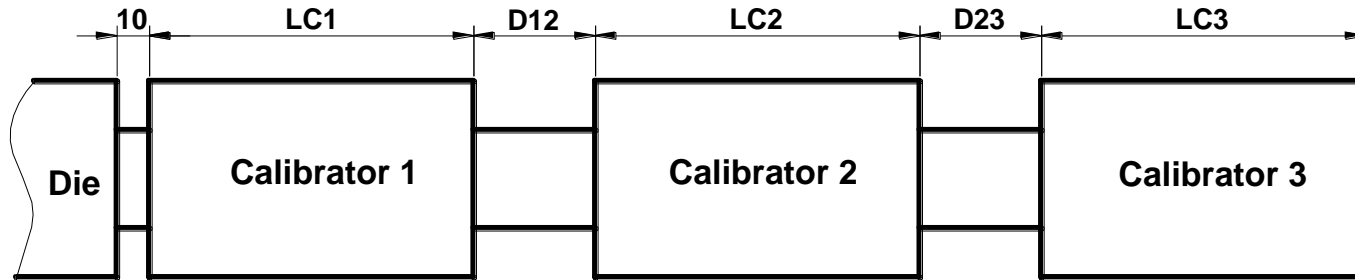




LC _i	LC1 [mm]	LC2 [mm]	LC3 [mm]
→	600	-	-
→	300	300	-
→	200	200	200
→	200	200	200
→	200	200	200
↘	300	200	100
↗	100	200	300
↘	300	200	100
↘	300	200	100
↗	100	200	300
↗	100	200	300

D _{ij}	D12 [mm]	D23 [mm]
→	240	-
→	120	120
↗	60	180
↘	180	60
→	120	120
→	120	120
↘	180	60
↗	60	180
↘	180	60
↗	60	180

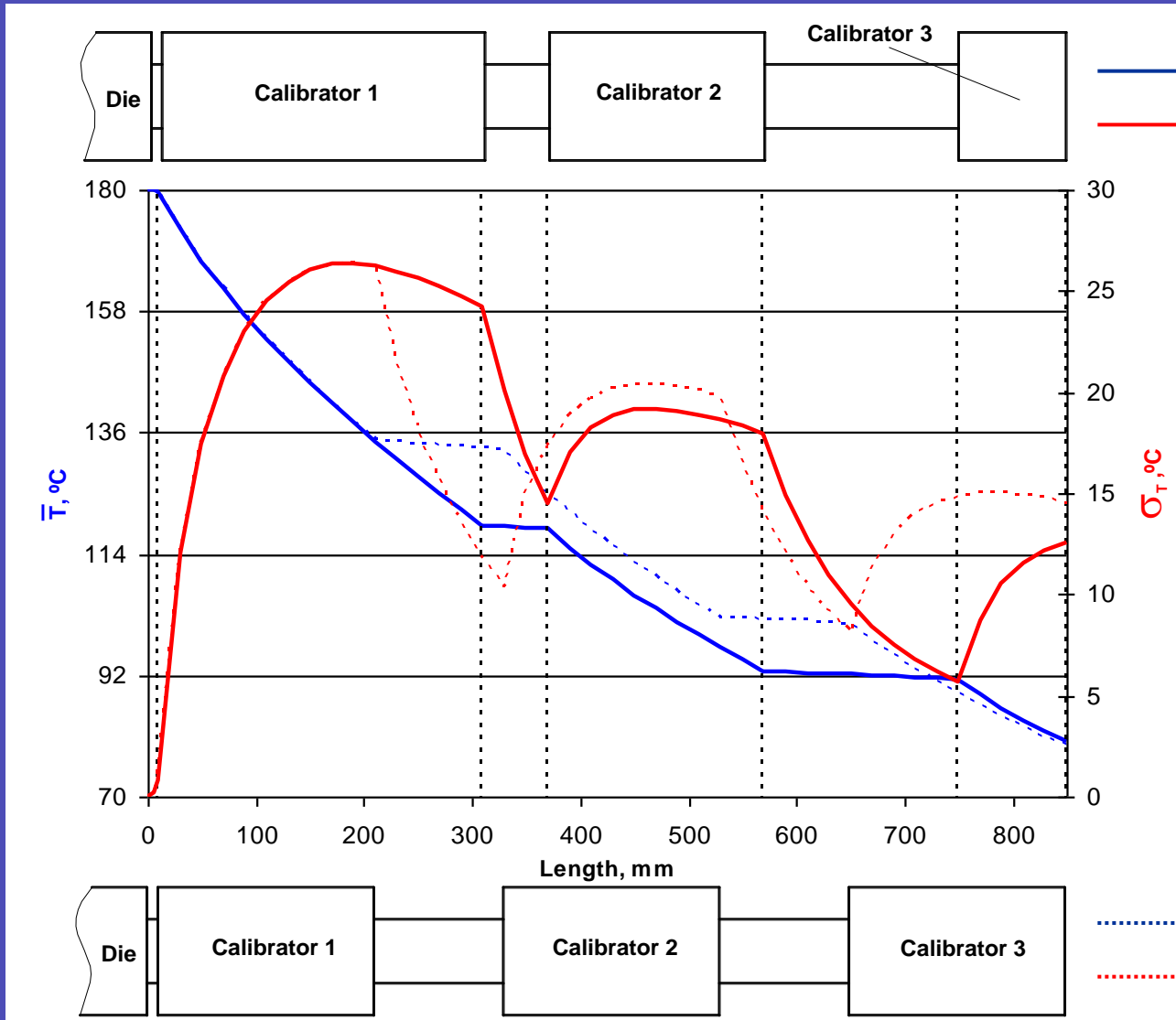
ΣLC_i (600 mm), ΣD (240 mm) (system length = 850 mm)



LC _i	LC1	LC2	LC3	D _{ij}	D12	D23	\bar{T}		σ_T	
	[mm]	[mm]	[mm]		[mm]	[mm]	[°C]	[%]	[°C]	[%]
→	600	-	-		-	-	84.9	0.0%	16.6	0.0%
→	300	300	-	→	240	-	80.3	-5.5%	15.2	-8.6%
→	200	200	200	→	120	120	79.2	-6.7%	14.5	-12.6%
→	200	200	200	↗	60	180	79.5	-6.4%	14.5	-13.1%
→	200	200	200	↘	180	60	79.4	-6.5%	14.8	-10.8%
↘	300	200	100	→	120	120	79.5	-6.4%	13.0	-22.1%
↗	100	200	300	→	120	120	79.4	-6.5%	15.1	-9.3%
↘	300	200	100	↘	180	60	79.6	-6.3%	13.8	-17.3%
↘	300	200	100	↗	60	180	79.9	-5.9%	12.6	-24.3%
↗	100	200	300	↘	180	60	79.7	-6.1%	15.2	-8.4%
↗	100	200	300	↗	60	180	79.5	-6.3%	15.1	-9.4%

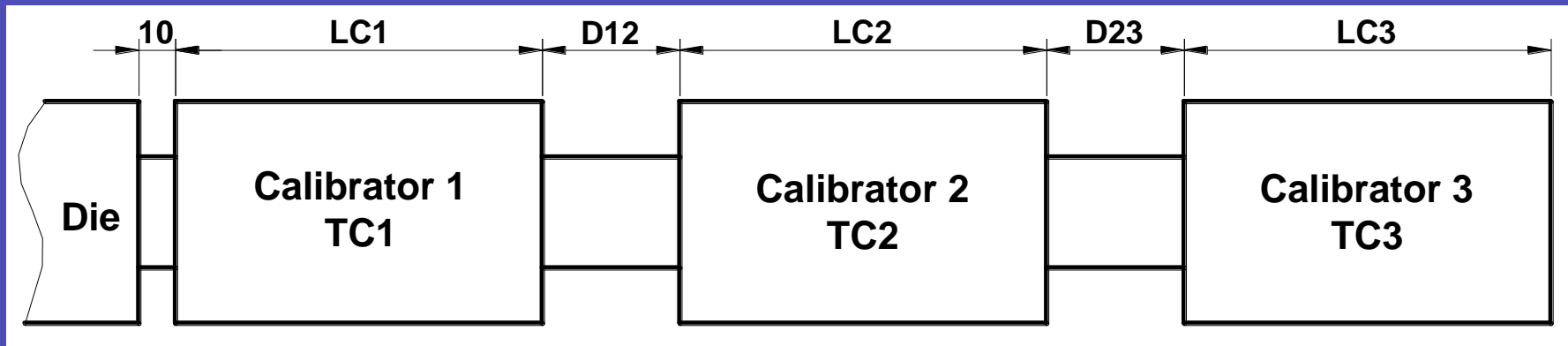
ΣLC_i (600 mm), ΣD (240 mm) (system length = 850 mm)

Calibrators - System Behaviour



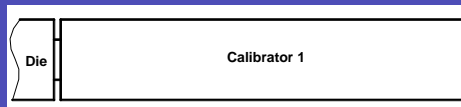


Influence of cooling fluid temperature T_{Ci}

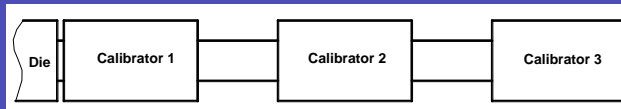




TCi	TC1	TC2	TC3
	[°C]	[°C]	[°C]



→	18	-	-
---	----	---	---



→ L_{Ci} + → D_{ij}

→	18	18	18
→	10	10	10
→	26	26	26
↘	26	18	10
↗	10	18	26

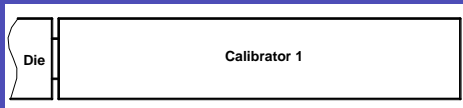


↘ L_{Ci} + ↗ D_{ij}

→	18	18	18
→	10	10	10
→	26	26	26
↘	26	18	10
↗	10	18	26

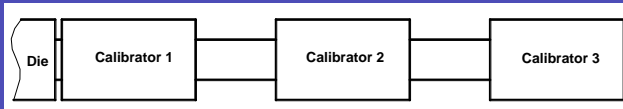
10°C ≤ TC_i ≤ 26°C

Calibrators - System Behaviour



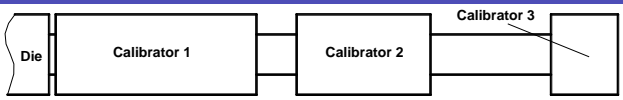
TCi	TC1	TC2	TC3	\bar{T}		σ_T	
	[°C]	[°C]	[°C]	[°C]	[%]	[°C]	[%]

→	18	-	-	84.9	-	16.6	-
---	----	---	---	------	---	------	---



→ L_{Ci} + → D_{ij}

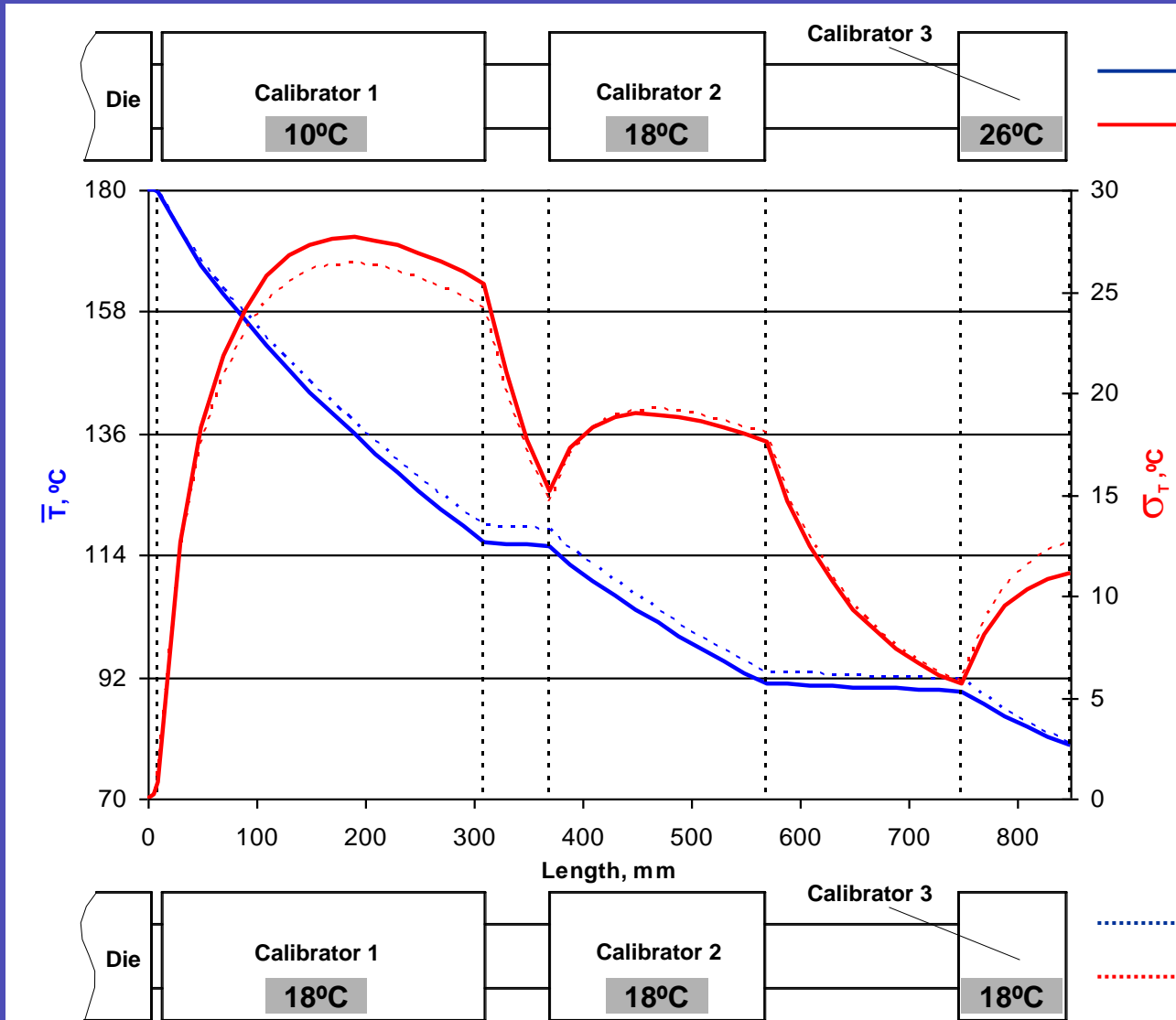
→	18	18	18	79.2	-6.7%	14.5	-12.6%
→	10	10	10	74.4	-12.3%	15.3	-8.2%
→	26	26	26	83.9	-1.1%	13.8	-17.0%
↘	26	18	10	78.0	-8.1%	16.0	-3.6%
↗	10	18	26	80.3	-5.4%	13.0	-21.7%



↘ L_{Ci} + ↗ D_{ij}

→	18	18	18	79.9	-5.9%	12.6	-24.3%
→	10	10	10	75.2	-11.4%	13.2	-20.7%
→	26	26	26	84.6	-0.4%	12.0	-28.0%
↘	26	18	10	80.2	-5.5%	14.1	-15.5%
↗	10	18	26	79.5	-6.3%	11.1	-33.1%

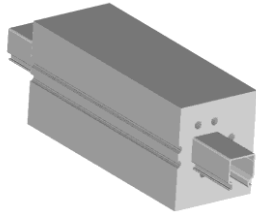
10°C ≤ TCi ≤ 26°C



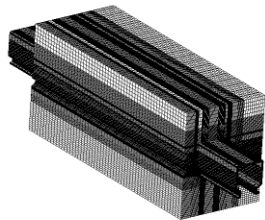


Input Data

Pre- Processor

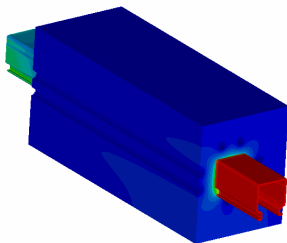


Geometry



Mesh

3D Temperature field calculation (FVM)



Temperature

Performance Evaluation

$$F_{obj} = \sum_{i=1}^n \alpha_i F_i$$

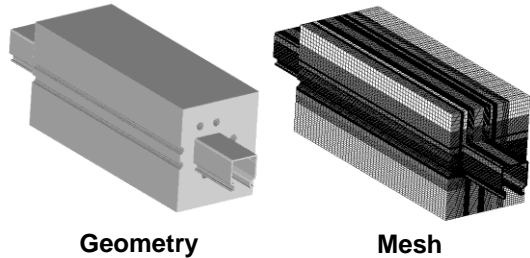
Optimisation: automatic generation of solutions (modification of the controllable geometrical parameters) until the optimum is reached





Input Data

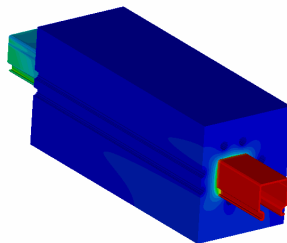
Pre-Processor



Geometry

Mesh

3D Temperature field calculation (FVM)



Temperature

Performance Evaluation

$$F_{obj} = \sum_{i=1}^n \alpha_i F_i$$

Optimisation: automatic generation of solutions (modification of the controllable geometrical parameters) until the optimum is reached

Temperature uniformity

$$\sigma_T = \sqrt{\frac{\sum_{i=1}^{n_f} (T_i - \bar{T})^2 A_i}{A_T}}$$

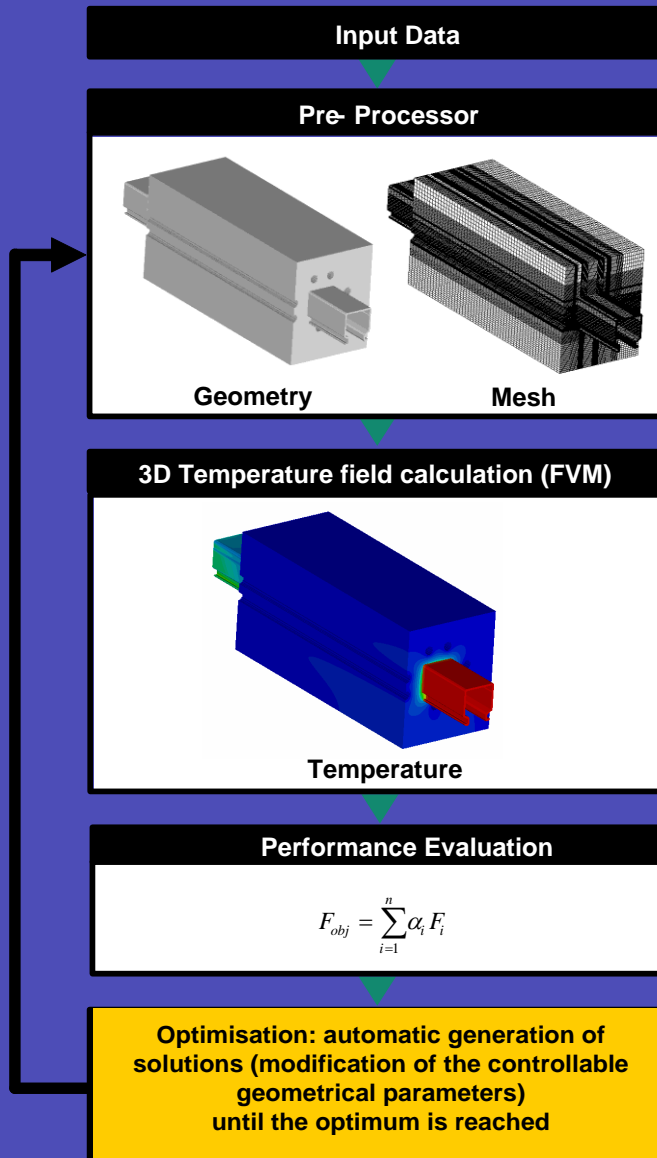
Cooling efficiency

$$\bar{T} = \frac{\sum_{i=1}^{n_f} T_i A_i}{A_T}$$

$$F_{obj} = K |\bar{T} - T_s| + \sigma_T$$

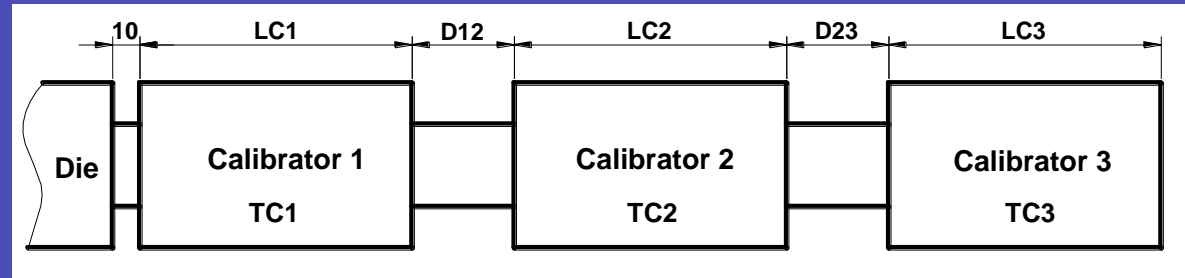
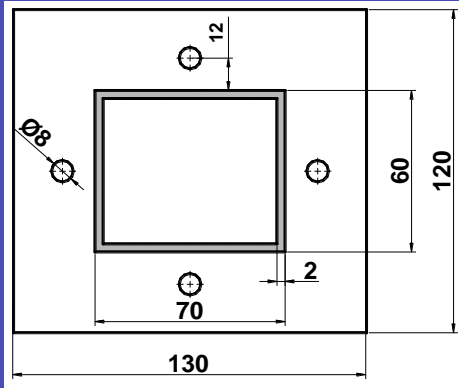
where:

$$\begin{cases} \bar{T} \leq T_s \Rightarrow K = 0 \\ \bar{T} > T_s \Rightarrow K = 1000 \end{cases}$$



Optimisation algorithm

Non-linear SIMPLEX method



Restrictions:

- Number of calibration/cooling units ≤ 3
- Total calibration length ($\sum LC_i$) ≤ 600 mm
- Total system length ($\sum LC_i + \sum D_{ij} + 10$) ≤ 850 mm
- Cooling Fluid Temperature $TC_i \in [10^\circ\text{C}, 26^\circ\text{C}]$



General conditions for the simulations

Processing conditions

$$v_p = 2 \text{ m/min}$$

$$T_m = 180 \text{ }^\circ\text{C}$$

$$T_f = 18 \text{ }^\circ\text{C}$$

$$T_s = 80 \text{ }^\circ\text{C}$$

Materials Properties

$$K_p = 0.18 \text{ W/mK}$$

$$K_c = 14 \text{ W/mK}$$

$$\rho_p = 1400 \text{ kg/m}^3$$

$$c_p = 1000 \text{ J/kgK}$$

Boundary conditions

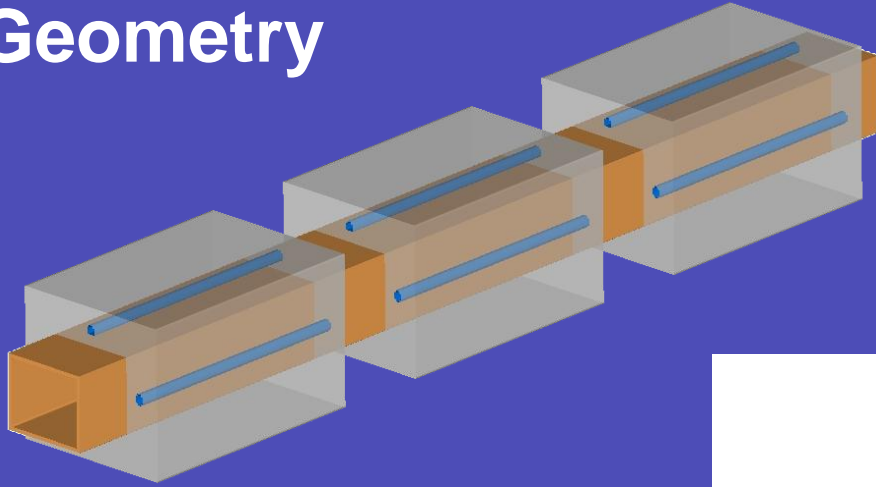
Annealing zones: free convection and radiation

Polymer-calibrator interface: contact resistance

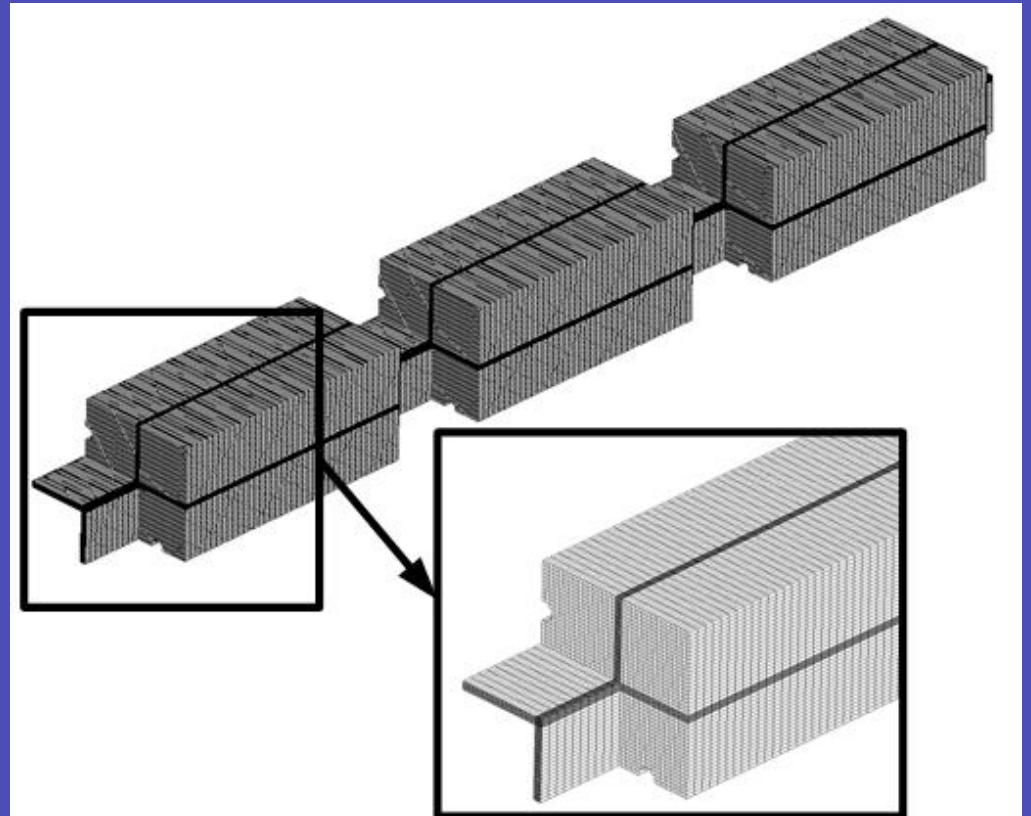
$$(h_i = 425 \text{ W/m}^2\text{K})$$

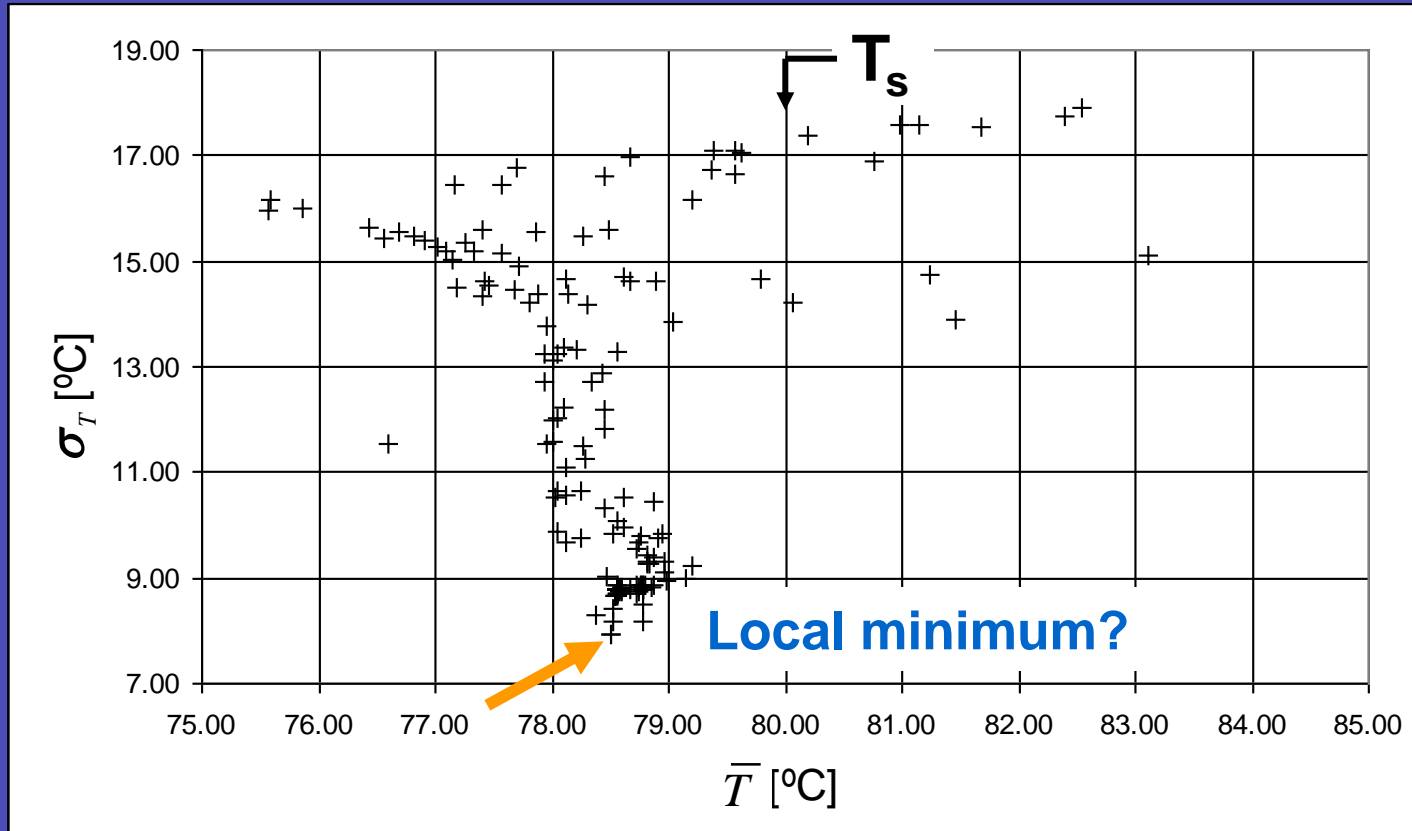


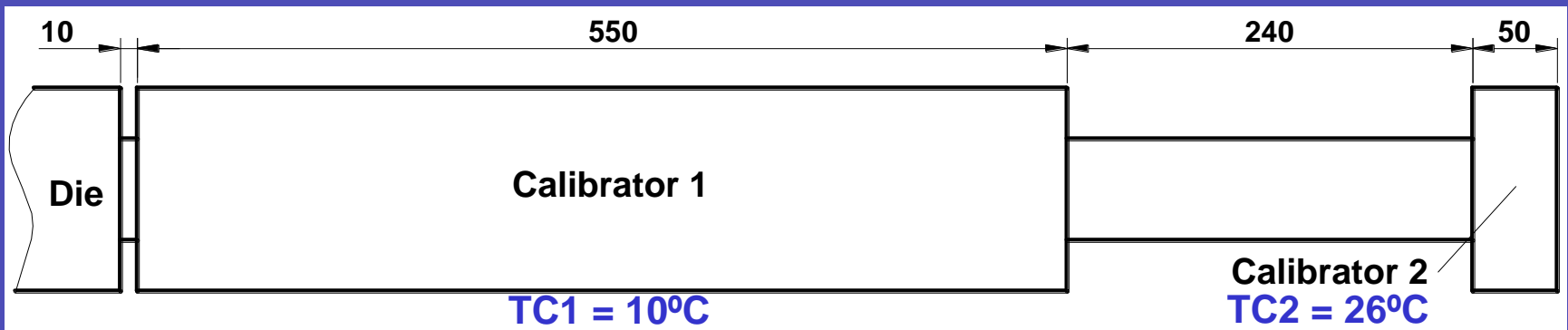
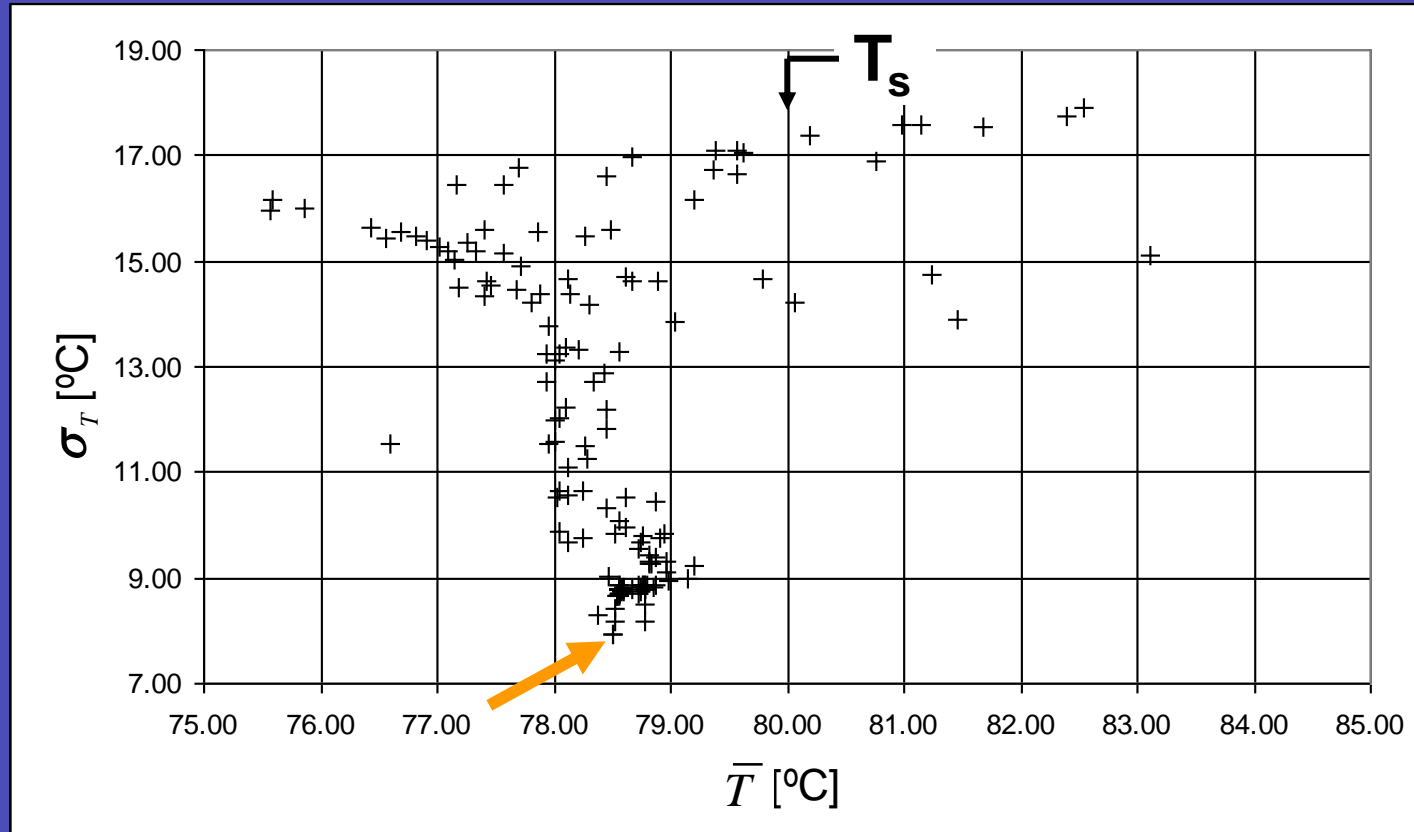
Geometry

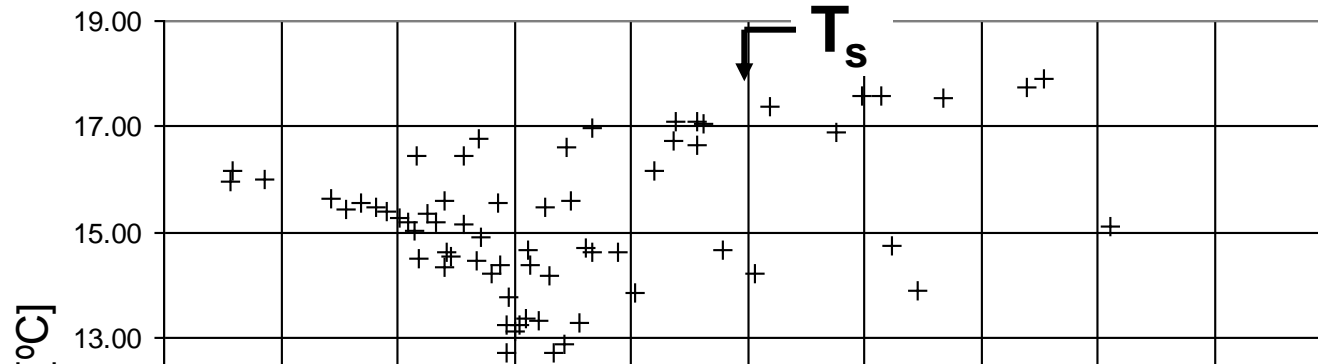


Mesh



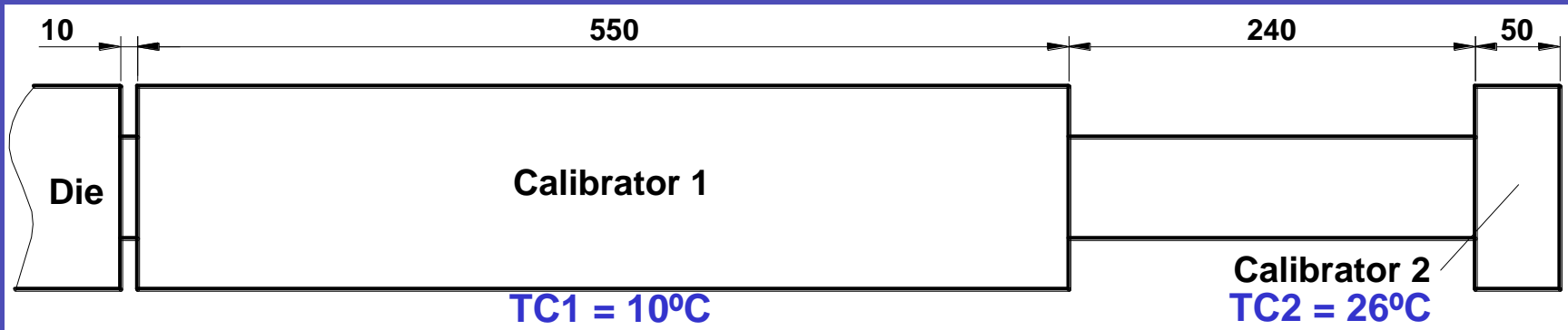






Geometry	\bar{T} [°C]	σ_T [°C]
One Calibrator (TC=18°C)	84.9	16.6
Optimum Solution	78.5	7.9

- 52.4%





- Cooling systems with
 - ascending cooling units lengths
 - descending annealing zone lengths
 - ascending cooling fluid temperaturesseem to have the best performance.



- The developed **optimisation methodologies** both for extrusion dies and calibrators were able to **improve automatically** the system performance;
- The **optimisation methodologies** are under development;
- The **employment of numerical analysis** allows a deeper insight of the process.



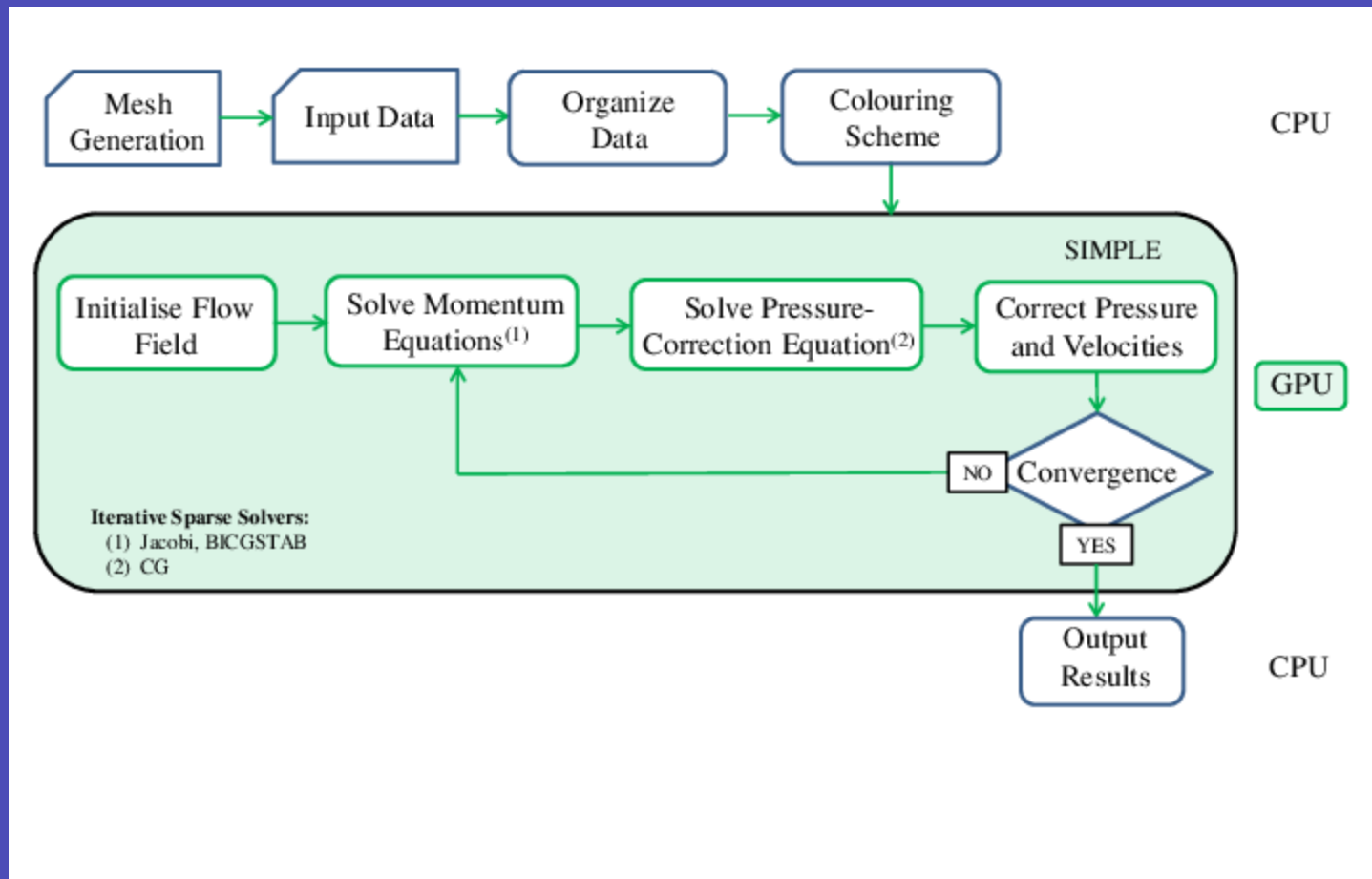
- **Implementation of the wall Slip and free-surface boundary conditions** (**L.L. Ferrás**, PhD project);
- **Development of unstructured numerical modelling code** (**N.D. Gonçalves**, PhD project);
- **Implementation of viscoelastic constitutive equations in an unstructured modelling code** (**S. Reddy**, MSc Eurheo project);
- **Prediction of thermal induced stresses in calibration in **OpenFOAM**** (**S. Reddy**, Research Project);
- **Development of high order interpolation schemes** (**B. Gubuz**, FCT Research Project);



- **Development of innovative parallelization approaches** (**R. Ribeiro**, PhD Project);
- **Development of multiscale modelling approaches** (**S.T. Mould + S.P. Pereira**, PhD Project);
- **Development of SPH numerical modelling code** (**D.F. Cordeiro**, PhD/Cooperation Project);
- **Development of FSI methodologies for the design of extrusion dies in **OpenFOAM**** (**M.R. Moosavi**, Post-doctoral project);
- **Modelling the cooling stage in profile extrusion using **OpenFOAM**** (**R. Ananth**, PhD project);



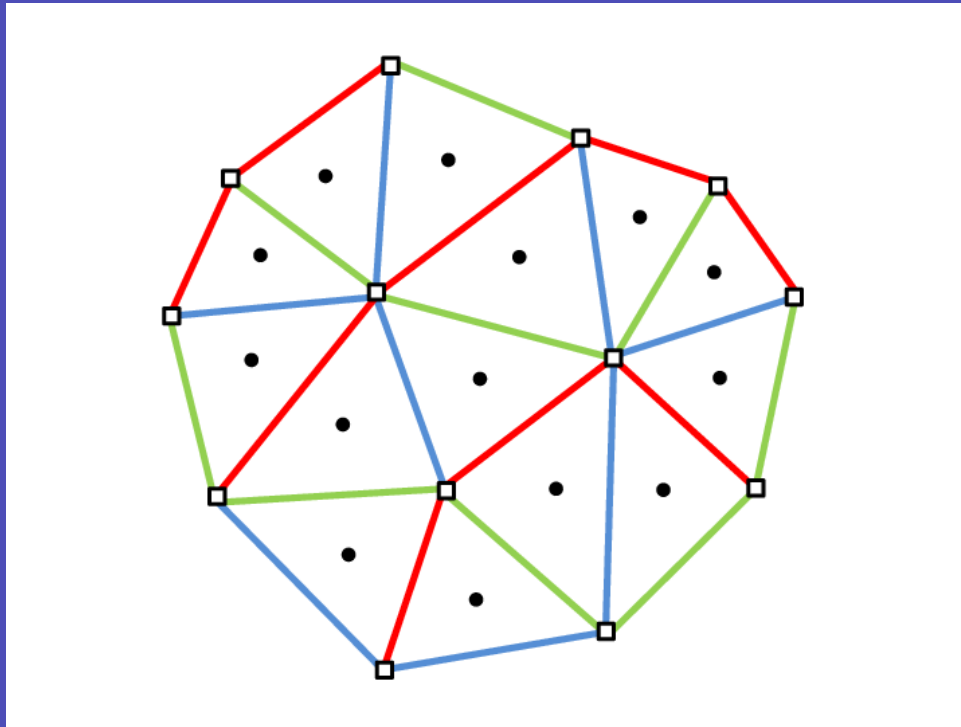
- Numerical code paralelization on GPU ([S.P. Pereira](#), FCT Research Project);





- Numerical code paralelization on GPU ([S.P. Pereira](#), FCT Research Project);

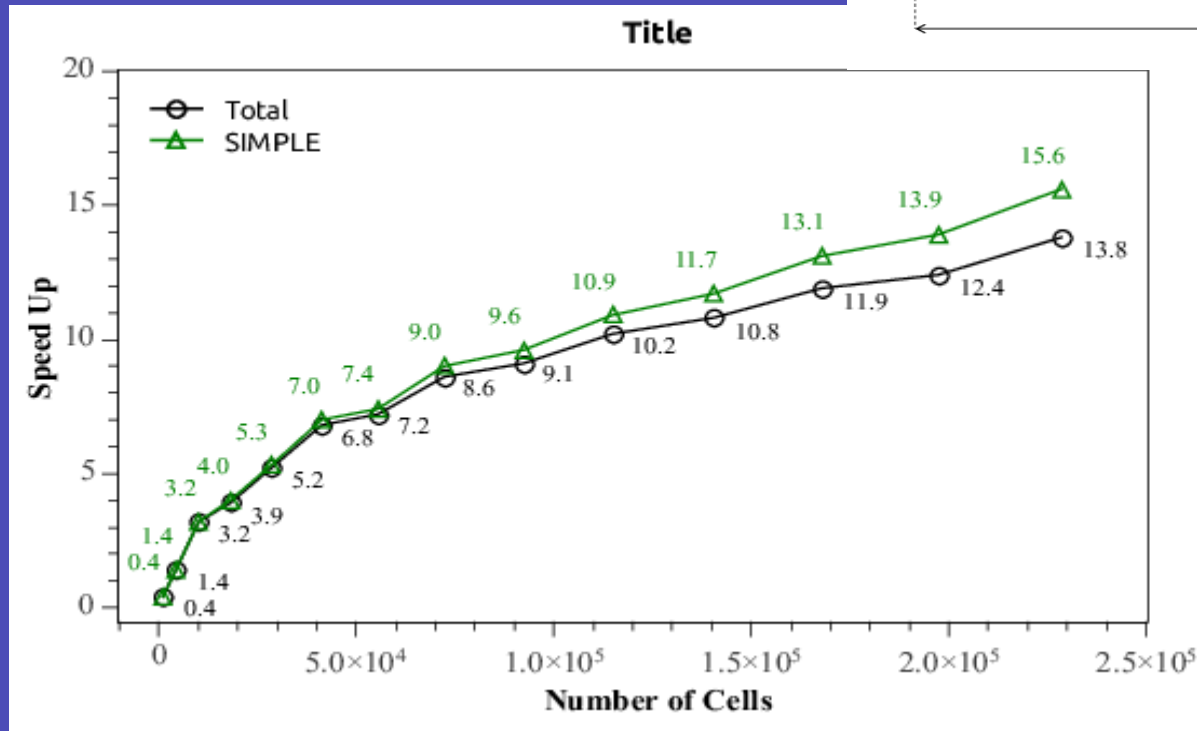
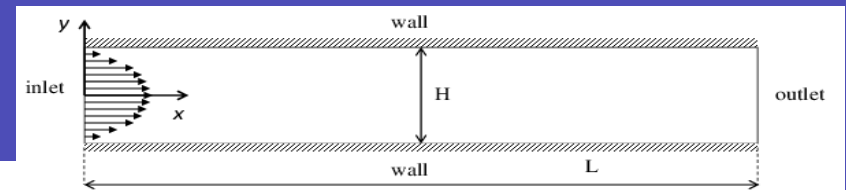
A colouring scheme was used to avoid race conditions





- Numerical code paralelization on GPU (S.P. Pereira, FCT Research Project);

Poiseuille Flow – Speed Up





- Numerical code paralelization on GPU ([S.P. Pereira](#), FCT Research Project);

Lid Driven Cavity Flow – Speed Up

