Processor Affinity

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Here are some notes on working with thread affinity to assure optimal performance of multithreaded codes.

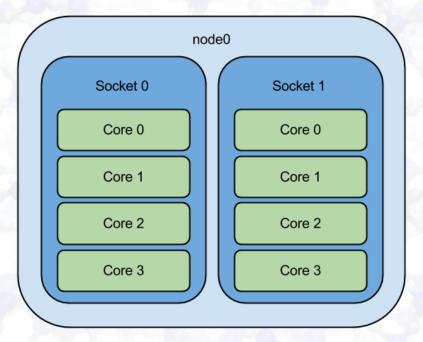
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Types of Thread Scheduling

Certain types of unevenly loaded applications can experience serious performance degradation caused by the Linux scheduler treating high-performance application codes in the same way it would treat a system daemon that might spend most of its time idle.

These sorts of scheduling issues are best described with diagrams. Let's assume we have compute nodes with two processor sockets, and each processor has four cores:



When you run a multithreaded application with four threads (or even four serial applications), Linux will *schedule* those threads for execution by assigning each one to a CPU core. Without being explicitly told how to do this scheduling, Linux may decide to

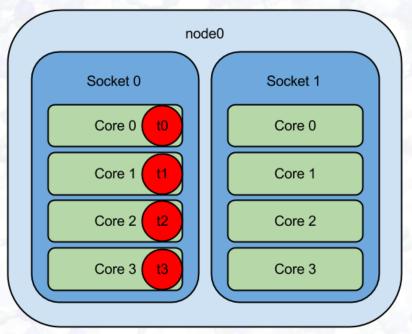
- 1. run thread0 to thread3 on core0 to core3 on socket0
- 2. run thread0 and thread1 on core0 and core1 on socket0, and run thread2 and thread3 on

- socket1 mun thread 0 and thread 1 an agree only mun thread 2 an agree 1 mun thread 2 an agree 2 and lague
- 3. <u>run thread0 and thread1 on core0 only, run thread2 on core1, run thread3 on core2, and leave core3 completely unutilized</u>
- 4. <u>any number of other nonsensical allocations involving assigning multiple threads to a single</u> <u>core while other cores sit idle</u>

It should be obvious that option #3 and #4 are very bad for performance, but the fact is that Linux will happily schedule your multithreaded job (or multiple single-thread jobs) this way if your threads behave in a way that is confusing to the operating system.

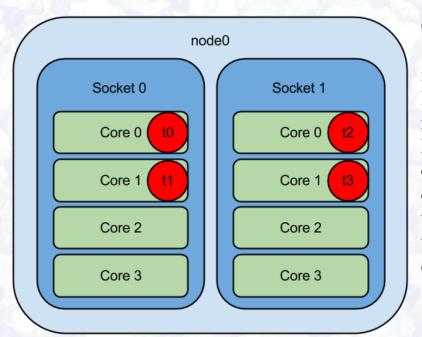
Compact Scheduling

Option #1 is often referred to as "compact" scheduling and is depicted in the diagram to the right. It keeps all of your threads running on a single physical processor if possible, and this is what you would want if all of the threads in your application need to repeatedly access different parts of a large array. This is because all of the cores on the same physical processor can access the memory banks associated with (or "owned by") that processor at the same speed. However, cores cannot access memory stored on memory banks owned by a different



processor as quickly; this is phenomenon is called NUMA (non-uniform memory access). If your threads all need to access data stored in the memory owned by one processor, it is often best to put all of your threads on the processor who owns that memory.

Round-Robin Scheduling



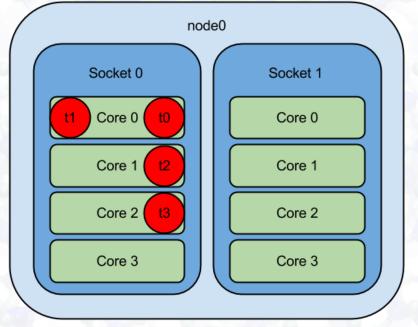
Option #2 is called "scatter" or "round-robin" scheduling and is ideal if your threads are largely independent of each other and don't need to access a lot of memory that other threads need. The benefit to round-robin thread scheduling is that not all threads have to share the same memory channel and cache, effectively doubling the memory bandwidth and cache sizes available to your application. The tradeoff is that memory latency becomes higher as threads have to start accessing memory that might be owned by another processor.

Stupid Scheduling

Option #3 and #4 are what I call "stupid" scheduling (see diagram to the right) and can often be the default behavior of the Linux thread scheduler if you don't tell Linux where your threads should run. This happens because in traditional Linux server environments, most of the processes that are running at any given time aren't doing anything. To conserve power, Linux will put a lot of these quiet processes on the same processor or cores, then move them to their own dedicated core when they wake up and have to start processing.

If your application is running at full bore 100% of the time, Linux will probably keep it on its own

dedicated CPU core. However, if your application has an uneven load (e.g., threads are mostly idle while the last thread finishes), Linux will see that the application is mostly quiet and pack all the quiet threads (e.g., t0 and t1 in the diagram to the right) on to the same CPU core. This wouldn't be so bad, but the cost of moving a thread from one core to another requires *context switches* which get very expensive when done hundreds or thousands of times a minute.



Determine current thread-core map

If your application (let's call it application.x) has already been launched, you can easily see what cores each thread is using by issuing the following command in bash:

```
$ for i in $(pgrep application.x); do ps -mo pid,tid,fname,user,psr -p
$i;done
```

The PSR field is the OS identifier for the core each TID (thread id) is utilizing.

Defining affinity

The Linux-Portable Way (taskset)

If you want to launch a job (e.g., simulation.x) on a certain set of cores (e.g., core0, core2, core4, and core6), issue

```
$ taskset -c 0,2,4,6 simulation.x
```

If your process is already running, you can define thread affinity while in flight. It also lets you bind specific TIDs to specific processors at a level of granularity greater than specifying -c 0,2,4,6 because Linux may still schedule two threads on core2 and nothing on core0. For example,

```
$ for i in $(pgrep application.x);do ps -mo pid,tid,fname,user,psr -p
   $i;done
       TID COMMAND USER
                             PSR
PID
21654 - applicat glock
   - 21654 -
                    glock
                               0
   - 21655 -
                  glock
                               2
                    glock
                               2
   - 21656 -
                               6
                    glock
   - 21657 -
   - 21658 -
                  glock
                               4
$ taskset -p -c 0 21654
$ taskset -p -c 0 21655
$ taskset -p -c 2 21656
$ taskset -p -c 4 21657
$ taskset -p -c 6 21658
```

This sort of scheduling will happen under certain conditions, so specifying a set of cpus to a set of threads without specifically assigning each thread to a physical core may not always behave optimally.

The Other Linux-Portable Way (numact1)

The emerging standard for easily binding processes to processors on Linux-based supercomputers is numact1. It can operate on a coarser-grained basis (i.e., CPU sockets rather than individual CPU cores) than taskset (only CPU cores) because it is aware of the processor topology and how the CPU cores map to CPU sockets. Using numact1 is typically easier--after all, the common goal is to confine a process to a numa pool (or "cpu node") rather than specific CPU cores. To that end, numact1 also lets you bind a processor's memory locality to prevent processes from having to jump across NUMA pools (called "memory nodes" in numact1 parlance).

Whereas if you wanted to bind a specific process to one processor socket with taskset you would have to

\$ taskset -c 0,2,4,6 simulation.x

the same operation is greatly simplified with numact1:

\$ numactl --cpunodebind=0 simulation.x

If you want to also restrict simulation.x's memory use to the numa pool associated with cpu node 0, you can do

```
$ numactl --cpunodebind=0 --membind=0 simulation.x
```

or just

```
$ numactl -C 0 -N 0 simulation.x
```

You can see what *cpu nodes* and their corresponding *memory nodes* are available on your system by using numactl -H:

```
$ numactl -H
available: 2 nodes (0-1)
node 0 size: 32728 MB
node 0 free: 12519 MB
node 1 size: 32768 MB
node 1 free: 16180 MB
node distances:
node 0 1
0: 10 21
1: 21 10
```

numactl also lets you supply specific cores (like taskset) with the --physcpubind or -C. Unlike taskset, though, numactl does not appear to let you change the CPU affinity of a process that is already running.

An alternative syntax to numactl -c is something like

\$ numactl -C +0,1,2,3 simulation.x

By prefixing your list of cores with a +, you can have numactl bind to *relative* cores. When combined with cpusets (which are enabled by default for all jobs on Gordon), the above command will use the 0th, 1st, 2nd, and 3rd core of the job's given cpuset instead of literally core 0,1,2,3.

Using OpenMP Runtime Extensions

Multithreaded programs compiled with Intel Compilers can utilize <u>Intel's Thread Affinity Interface</u> for OpenMP applications. Set and export the KMP_AFFINITY env variable to express binding preferences. KMP_AFFINITY has three principal binding strategies:

- compact fills up one socket before allocating to other sockets
- scatter evenly spreads threads across all sockets and cores
- explicit allows you define exactly which cores/sockets to use

Using KMP_AFFINITY=compact will preferentially bind all your threads, one per core, to a single socket before it tries binding them to other sockets. Unfortunately, it will start at socket0 regardless of if other processes (such as another SMP job) is already bound to that socket. You can explicitly specify an offset to force the job to bind to a specific socket, but you need to know exactly what is running on what cores and sockets on your node in order to specify this in your submit script.

You can also explicitly define which cores your job should use. Combined with a little knowledge of your system's CPU topology (Intel's <u>Processor Topology Enumeration tool</u> is great for this). If you wanted to run on cores 0, 2, 4, and 6, you would do

export KMP AFFINITY='proclist=[0,2,4,6],explicit'

GNU's implementation of OpenMP has a environment variable similar to KMP_AFFINITY called GOMP_CPU_AFFINITY. Incidentally, Intel's OpenMP supports GOMP_CPU_AFFINITY, so using this variable may be a relatively portable way to specify thread affinity at runtime. The equivalent GOMP_CPU_AFFINITY for the KMP_AFFINITY I gave above would be:

export GOMP_CPU_AFFINITY='0,2,4,6'

.

getfreesocket

I wrote <u>a small perl script called getfreesocket</u> that uses KMP_AFFINITY=explicit (or GOMP_CPU_AFFINITY) and some probing of the Linux OS at runtime to intelligently bind SMP jobs to free processor sockets. It should be invoked in a run script something like this:

```
#!/bin/bash
```

NPROCS=1 BINARY=\${HOME}/bin/whatever

```
nprocs=$(grep '^physical id' /proc/cpuinfo | sort -u | wc -1)
ncores=$(grep '^processor' /proc/cpuinfo | sort -u | wc -1)
coresperproc=$((ncores/nprocs))
```

```
OMP_NUM_THREADS=$((NPROCS*coresperproc))
freesock=$(getfreesocket -explicit=${NPROCS})
if [ "z$freesock" == "z" ]
then
    echo "Not enough free processors! aborting"
    exit 1
else
    KMP_AFFINITY="granularity=fine,proclist=[$freesock],explicit"
    GOMP_CPU_AFFINITY="$(echo $freesock | sed -e 's/,//g')"
fi
export KMP_AFFINITY OMP_NUM_THREADS GOMP_CPU_AFFINITY
${BINARY}
```

This was a very simple solution to get single-socket jobs to play nicely on the shared batch system we were using at the <u>Interfacial Molecular Science Laboratory</u>. While numactl is an easier way to accomplish some of this, it still requires that you know what other processes are sharing your node and on what CPU cores they are running. I've experienced problems with <u>Linux's braindead thread</u> <u>scheduling</u> so this getfreesocket intelligently finds completely unused sockets that can be fed into taskset, KMP AFFINITY, or numactl.

This is not as great an issue if your resource manager supports launching jobs within cpusets. Your resource manager will provide a cpuset, and using relative specifiers for numactl cores (e.g., numactl -c +0-3) will bind to the free socket provided by the batch environment. Of course, this will not specifically bind one thread to one core, so using KMP_AFFINITY or GOMP_CPU_AFFINITY may remain necessary.

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