

Análise do desempenho de execução de aplicações (adaptado das aulas 10, 11 e 18 do Bryant)

- "Análise de desempenho": para quê?
 - para construir computadores mais rápidos
 - identificação de métricas
 - latência, velocidade, ...
 - ligação entre métricas e factores que influenciam o desempenho
 - $\text{CPU}_{\text{Time}} = N^{\circ}_{\text{instr}} * \text{CPI} * T_{\text{clock}}$
 - para melhorar o desempenho das aplicações
 - análise de técnicas de optimização
 - independentes / dependentes da máquina
 - algoritmo / codificação / compilação / *assembly*
 - técnicas de medição
 - escala microscópica / macroscópica
 - uso de *cycle counters* / *interval counting*

Os próximos slides
foram retirados da
aula do Prof. Bryant

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Code Optimization I: Machine Independent Optimizations Sept. 26, 2002

Topics

- Machine-Independent Optimizations
 - Code motion
 - Reduction in strength
 - Common subexpression sharing
- Tuning
 - Identifying performance bottlenecks

Optimizing Compilers

- Provide efficient mapping of program to machine
 - register allocation
 - code selection and ordering
 - eliminating minor inefficiencies
- Don't (usually) improve asymptotic efficiency
 - up to programmer to select best overall algorithm
 - big-O savings are (often) more important than constant factors
 - but constant factors also matter
- Have difficulty overcoming "optimization blockers"
 - potential memory aliasing
 - potential procedure side-effects

Machine-Independent Optimizations

- Optimizations you should do regardless of processor / compiler
- Code Motion
 - Reduce frequency with which computation performed
 - If it will always produce same result
 - Especially moving code out of loop

```
for (i = 0; i < n; i++)  
  for (j = 0; j < n; j++)  
    a[n*i + j] = b[j];
```



```
for (i = 0; i < n; i++) {  
  int ni = n*i;  
  for (j = 0; j < n; j++)  
    a[ni + j] = b[j];  
}
```

Compiler-Generated Code Motion

- Most compilers do a good job with array code + simple loop structures

Code Generated by GCC

```
for (i = 0; i < n; i++)
  for (j = 0; j < n; j++)
    a[n*i + j] = b[j];
```

```
for (i = 0; i < n; i++) {
  int ni = n*i;
  int *p = a+ni;
  for (j = 0; j < n; j++)
    *p++ = b[j];
}
```

```
imull %ebx,%eax    # i*n
movl 8(%ebp),%edi  # a
leal (%edi,%eax,4),%edx # p = a+i*n (scaled by 4)
# Inner Loop
.L40:
movl 12(%ebp),%edi # b
movl (%edi,%ecx,4),%eax # b+j (scaled by 4)
movl %eax,(%edx)    # *p = b[j]
addl $4,%edx       # p++ (scaled by 4)
incl %ecx          # j++
jle .L40           # loop if j<n
```

Reduction in Strength

- Replace costly operation with simpler one
- Shift, add instead of multiply or divide
 - $16 * x \rightarrow x \ll 4$
 - Utility machine dependent
 - Depends on cost of multiply or divide instruction
 - On Pentium II or III, integer multiply only requires 4 CPU cycles
- Recognize sequence of products

```
for (i = 0; i < n; i++)
  for (j = 0; j < n; j++)
    a[n*i + j] = b[j];
```

```
int ni = 0;
for (i = 0; i < n; i++) {
  for (j = 0; j < n; j++)
    a[ni + j] = b[j];
  ni += n;
}
```

Make Use of Registers

- Reading and writing registers much faster than reading/writing memory
- Limitation
 - Compiler not always able to determine whether variable can be held in register
 - Possibility of *Aliasing*
 - See example later

Machine-Independent Opts. (Cont.)

- Share Common Subexpressions
 - Reuse portions of expressions
 - Compilers often not very sophisticated in exploiting arithmetic properties

```
/* Sum neighbors of i,j */
up = val[(i-1)*n + j];
down = val[(i+1)*n + j];
left = val[i*n + j-1];
right = val[i*n + j+1];
sum = up + down + left + right;
```

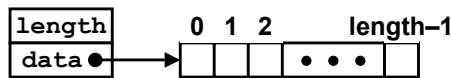
3 multiplications: $i*n$, $(i-1)*n$, $(i+1)*n$

```
int inj = i*n + j;
up = val[inj - n];
down = val[inj + n];
left = val[inj - 1];
right = val[inj + 1];
sum = up + down + left + right;
```

1 multiplication: $i*n$

```
leal -1(%edx),%ecx # i-1
imull %ebx,%ecx   # (i-1)*n
leal 1(%edx),%eax # i+1
imull %ebx,%eax   # (i+1)*n
imull %ebx,%edx   # i*n
```

Vector ADT



- Procedures

```
vec_ptr new_vec(int len)
```

- Create vector of specified length

```
int get_vec_element(vec_ptr v, int index, int *dest)
```

- Retrieve vector element, store at *dest
- Return 0 if out of bounds, 1 if successful

```
int *get_vec_start(vec_ptr v)
```

- Return pointer to start of vector data
- Similar to array implementations in Pascal, ML, Java
 - E.g., always do bounds checking

Optimization Example

```
void combinel(vec_ptr v, int *dest)
{
    int i;
    *dest = 0;
    for (i = 0; i < vec_length(v); i++) {
        int val;
        get_vec_element(v, i, &val);
        *dest += val;
    }
}
```

- Procedure

- Compute sum of all elements of vector
- Store result at destination location

Time Scales

- Absolute Time

- Typically use nanoseconds
 - 10^{-9} seconds
- Time scale of computer instructions

- Clock Cycles

- Most computers controlled by high frequency clock signal
- Typical Range
 - 100 MHz
 - 10^8 cycles per second
 - Clock period = 10ns
 - 2 GHz
 - 2×10^9 cycles per second
 - Clock period = 0.5ns

Cycles Per Element ⁽¹⁾

- C code for the vector sum functions

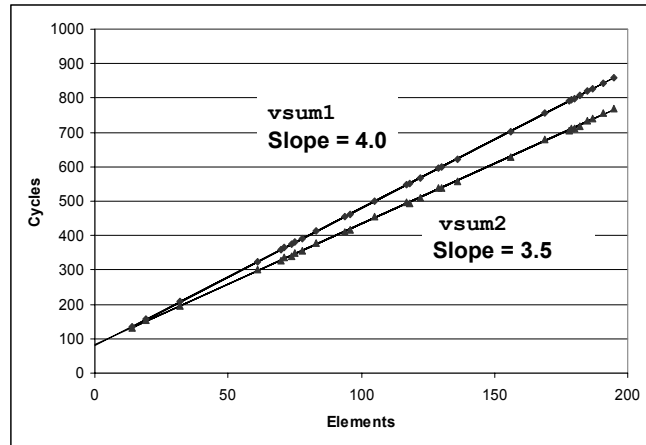
code/opt/vsum.c

```
1 void vsum1(int n)
2 {
3     int i;
4
5     for (i = 0; i < n; i++)
6         c[i] = a[i] + b[i];
7 }
8
9 /* Sum vector of n elements (n must be even) */
10 void vsum2(int n)
11 {
12     int i;
13
14     for (i = 0; i < n; i+=2) {
15         /* Compute two elements per iteration */
16         c[i] = a[i] + b[i];
17         c[i+1] = a[i+1] + b[i+1];
18     }
19 }
```

code/opt/vsum.c

Cycles Per Element ⁽²⁾

- Convenient way to express performance of program that operators on vectors or lists
- Length = n
- $T = CPE * n + \text{Overhead}$



Optimization Example

```
void combinel(vec_ptr v, int *dest)
{
    int i;
    *dest = 0;
    for (i = 0; i < vec_length(v); i++) {
        int val;
        get_vec_element(v, i, &val);
        *dest += val;
    }
}
```

- Procedure
 - Compute sum of all elements of integer vector
 - Store result at destination location
 - Vector data structure and operations defined via abstract data type
- Pentium II/III Performance: Clock Cycles / Element
 - 42.06 (Compiled -g) 31.25 (Compiled -O2)

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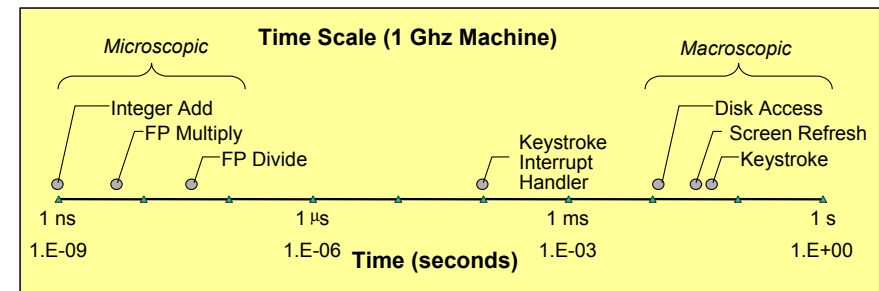
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Time Measurement Oct. 24, 2002

Topics

- Time scales
- Interval counting
- Cycle counters
- K-best measurement scheme

Computer Time Scales



- Two Fundamental Time Scales
 - Processor: $\sim 10^{-9}$ sec.
 - External events: $\sim 10^{-2}$ sec.
- Implication
 - Can execute many instructions while waiting for external event to occur
 - Can alternate among processes without anyone noticing

Cycle Counters

- Most modern systems have built in registers that are incremented every clock cycle
 - Very fine grained
 - Maintained as part of process state
 - In Linux, counts elapsed global time
- Special assembly code instruction to access
- On (recent model) Intel machines:
 - 64 bit counter.
 - RDTSC instruction sets `%edx` to high order 32-bits, `%eax` to low order 32-bits

Cycle Counter Period

- Wrap Around Times for 550 MHz machine
 - Low order 32 bits wrap around every $2^{32} / (550 * 10^6) = 7.8$ seconds
 - High order 64 bits wrap around every $2^{64} / (550 * 10^6) = 33539534679$ seconds
 - 1065 years
- For 2 GHz machine
 - Low order 32-bits every 2.1 seconds
 - High order 64 bits every 293 years

Measuring with Cycle Counter

- Idea
 - Get current value of cycle counter
 - store as pair of unsigned's `cyc_hi` and `cyc_lo`
 - Compute something
 - Get new value of cycle counter
 - Perform double precision subtraction to get elapsed cycles

```
/* Keep track of most recent reading of cycle counter */
static unsigned cyc_hi = 0;
static unsigned cyc_lo = 0;

void start_counter()
{
    /* Get current value of cycle counter */
    access_counter(&cyc_hi, &cyc_lo);
}
```

Accessing the Cycle Cntr.

- GCC allows inline assembly code with mechanism for matching registers with program variables
- Code only works on x86 machine compiling with GCC

```
void access_counter(unsigned *hi, unsigned *lo)
{
    /* Get cycle counter */
    asm("rdtsc; movl %%edx,%0; movl %%eax,%1"
        : "=r" (*hi), "=r" (*lo)
        : /* No input */
        : "%edx", "%eax");
}
```

- Emit assembly with `rdtsc` and two `movl` instructions

Closer Look at Extended ASM

```
asm("Instruction String"  
  : Output List  
  : Input List  
  : Clobbers List);  
}
```

```
void access_counter  
(unsigned *hi, unsigned *lo)  
{  
  /* Get cycle counter */  
  asm("rdtsc; movl %%edx,%0; movl %%eax,%1"  
    : "=r" (*hi), "=r" (*lo)  
    : /* No input */  
    : "%edx", "%eax");  
}
```

- Instruction String
 - Series of assembly commands
 - Separated by ";" or "\n"
 - Use "%%" where normally would use "%"

Closer Look at Extended ASM

```
asm("Instruction String"  
  : Output List  
  : Input List  
  : Clobbers List);  
}
```

```
void access_counter  
(unsigned *hi, unsigned *lo)  
{  
  /* Get cycle counter */  
  asm("rdtsc; movl %%edx,%0; movl %%eax,%1"  
    : "=r" (*hi), "=r" (*lo)  
    : /* No input */  
    : "%edx", "%eax");  
}
```

- Output List
 - Expressions indicating destinations for values %0, %1, ..., %j
 - Enclosed in parentheses
 - Must be *lvalue*
 - Value that can appear on LHS of assignment
 - Tag "=r" indicates that symbolic value (%0, etc.), should be replaced by register

Closer Look at Extended ASM

```
asm("Instruction String"  
  : Output List  
  : Input List  
  : Clobbers List);  
}
```

```
void access_counter  
(unsigned *hi, unsigned *lo)  
{  
  /* Get cycle counter */  
  asm("rdtsc; movl %%edx,%0; movl %%eax,%1"  
    : "=r" (*hi), "=r" (*lo)  
    : /* No input */  
    : "%edx", "%eax");  
}
```

- Input List
 - Series of expressions indicating sources for values %j+1, %j+2, ...
 - Enclosed in parentheses
 - Any expression returning value
 - Tag "r" indicates that symbolic value (%0, etc.) will come from register

Closer Look at Extended ASM

```
asm("Instruction String"  
  : Output List  
  : Input List  
  : Clobbers List);  
}
```

```
void access_counter  
(unsigned *hi, unsigned *lo)  
{  
  /* Get cycle counter */  
  asm("rdtsc; movl %%edx,%0; movl %%eax,%1"  
    : "=r" (*hi), "=r" (*lo)  
    : /* No input */  
    : "%edx", "%eax");  
}
```

- Clobbers List
 - List of register names that get altered by assembly instruction
 - Compiler will make sure doesn't store something in one of these registers that must be preserved across `asm`
 - Value set before & used after

Accessing the Cycle Cntr. (cont.)

- Emitted Assembly Code

```
movl 8(%ebp),%esi    # hi
movl 12(%ebp),%edi   # lo
#APP
    rdtsc; movl %edx,%ecx; movl %eax,%ebx
#NO_APP
    movl %ecx,(%esi)    # Store high bits at *hi
    movl %ebx,(%edi)    # Store low bits at *lo
```

- Used %ecx for *hi (replacing %0)
- Used %ebx for *lo (replacing %1)
- Does not use %eax or %edx for value that must be carried across inserted assembly code

Completing Measurement

- Get new value of cycle counter
- Perform double precision subtraction to get elapsed cycles
- Express as double to avoid overflow problems

```
double get_counter()
{
    unsigned ncyc_hi, ncyc_lo
    unsigned hi, lo, borrow;
    /* Get cycle counter */
    access_counter(&ncyc_hi, &ncyc_lo);
    /* Do double precision subtraction */
    lo = ncyc_lo - cyc_lo;
    borrow = lo > ncyc_lo;
    hi = ncyc_hi - cyc_hi - borrow;
    return (double) hi * (1 << 30) * 4 + lo;
}
```

Timing With Cycle Counter

- Determine Clock Rate of Processor
 - Count number of cycles required for some fixed number of seconds

```
double MHZ;
int sleep_time = 10;
start_counter();
sleep(sleep_time);
MHZ = get_counter() / (sleep_time * 1e6);
```

- Time Function P
 - First attempt: Simply count cycles for one

```
double tsecs;
start_counter();
P();
tsecs = get_counter() / (MHZ * 1e6);
```